



Introduction to mechanical testing of soft solid polymers

Costantino Creton

Laboratory of Soft Matter Science and Engineering

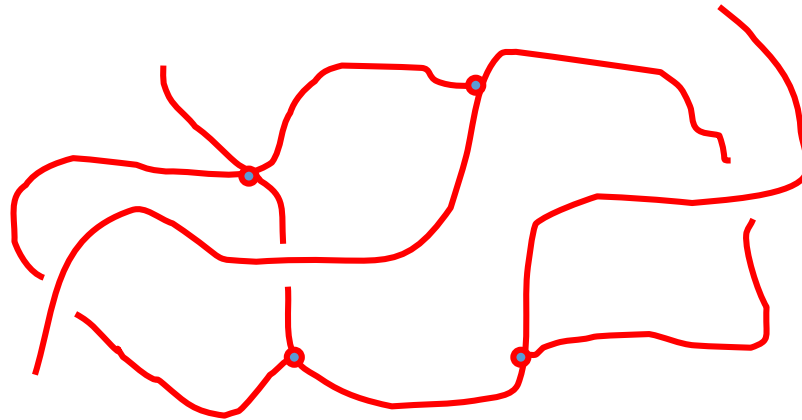
ESPCI Paris, (France)



<http://ccreton.simm.espci.fr/>

Soft Polymer Materials

Mechanical properties dominated by entropic elasticity:



Crosslink points (covalent)

Hydrogen bonds

Specific interactions

Physical crosslinks

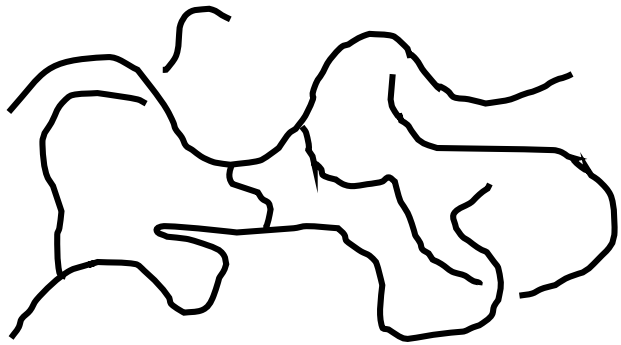
Entanglements (relaxing)

Simple physicist's view: a collection of Gaussian chains , $E \sim kT$ per chain

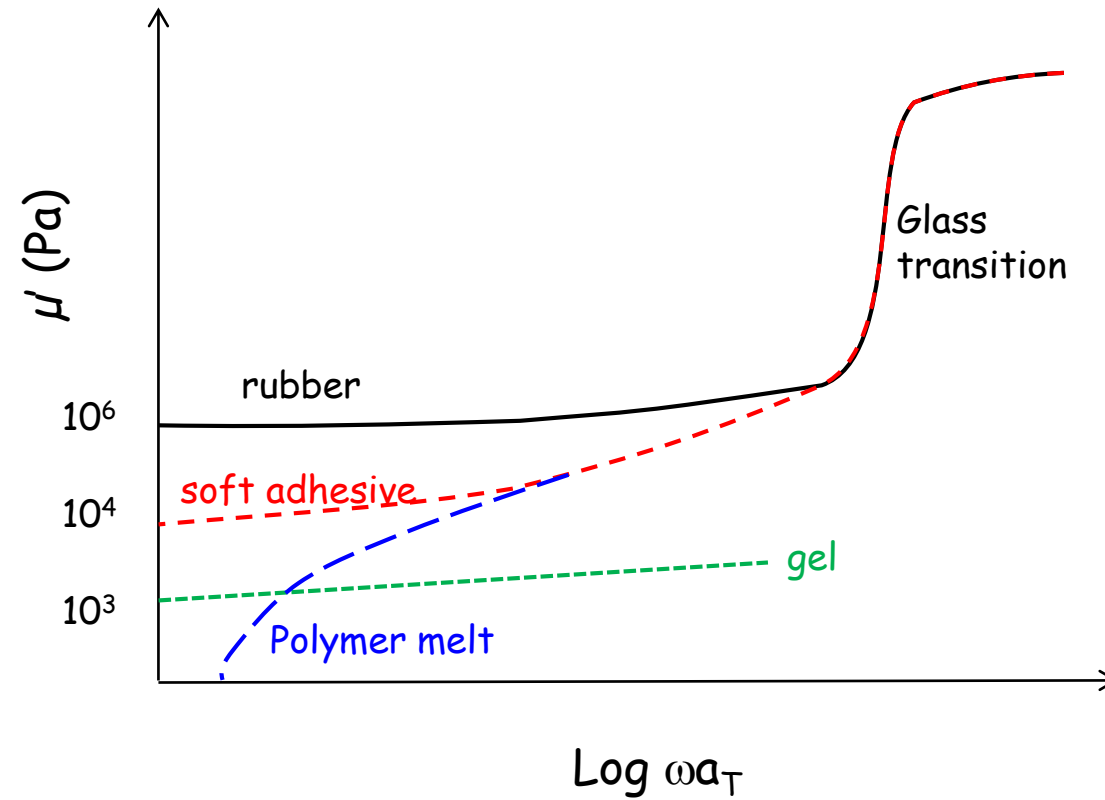
Simple view of a viscoelastic network: The effective number of elastic chains varies due to relaxation ($E = f(t)$)

Complex network with finite extensibility of chains and bonds of variable strength

Moduli are in the range of 1 kPa to 1 Mpa

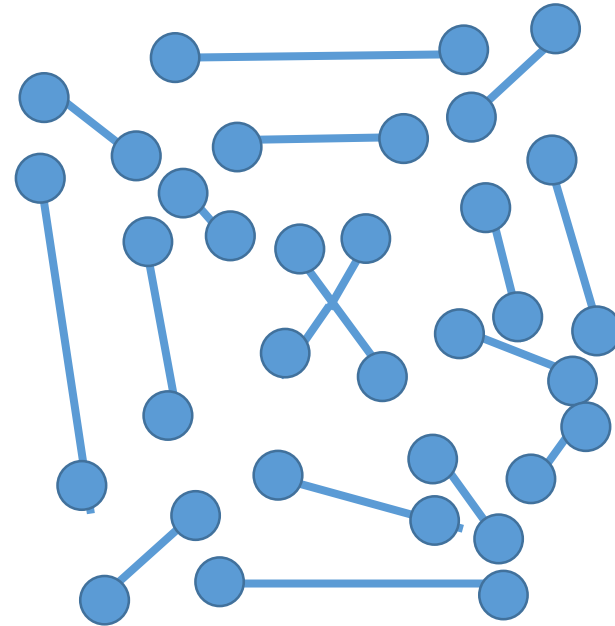
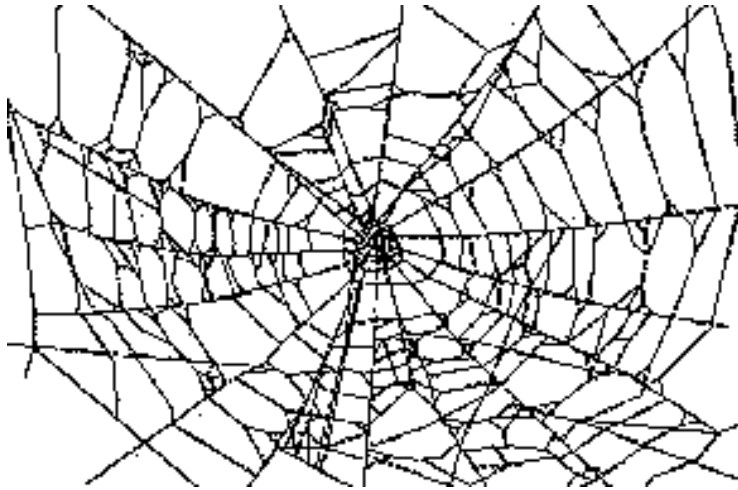


Entanglements can relax the stress while solvent swelling
Reduces the density of elastic chains



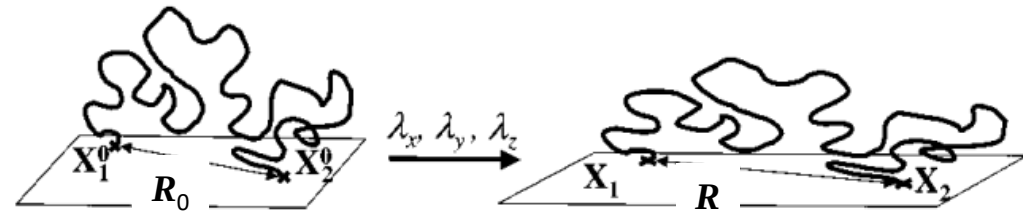
Elasticity of Polymer Networks

Affine network model



Mean-field models

The strand ends are attached to
affinely deformed background



Change of network free energy

$$R_i = \lambda_i R_{0i}$$

$$\Delta F_{aff} = kT \sum_i \left(\frac{3R_i^2}{2b^2n} - \frac{3R_{i0}^2}{2b^2n} \right) = \frac{kT}{2} \sum_i (\lambda_i^2 - 1) \frac{3R_{i0}^2}{b^2n} = \frac{kT}{2} \nu V \sum_i (\lambda_i^2 - 1)$$

since for random cross-linking $\langle R_{i0} R_{j0} \rangle = \frac{1}{3} b^2 n \delta_{ij}$

Uniaxial network deformation $\lambda_x = \lambda$, $\lambda_y = \lambda_z = \lambda^{-1/2}$. Stress is the derivative $\partial(\Delta F)/\partial L_x$ (force), divided by the cross-sectional area of the sample $L_y L_z$.

$$\sigma = \frac{1}{L_y L_z} \frac{\partial \Delta F}{\partial L_x} = \frac{1}{L_y L_z L_x} \frac{\partial \Delta F}{\partial \lambda} = \frac{1}{V} \frac{\partial \Delta F}{\partial \lambda}$$

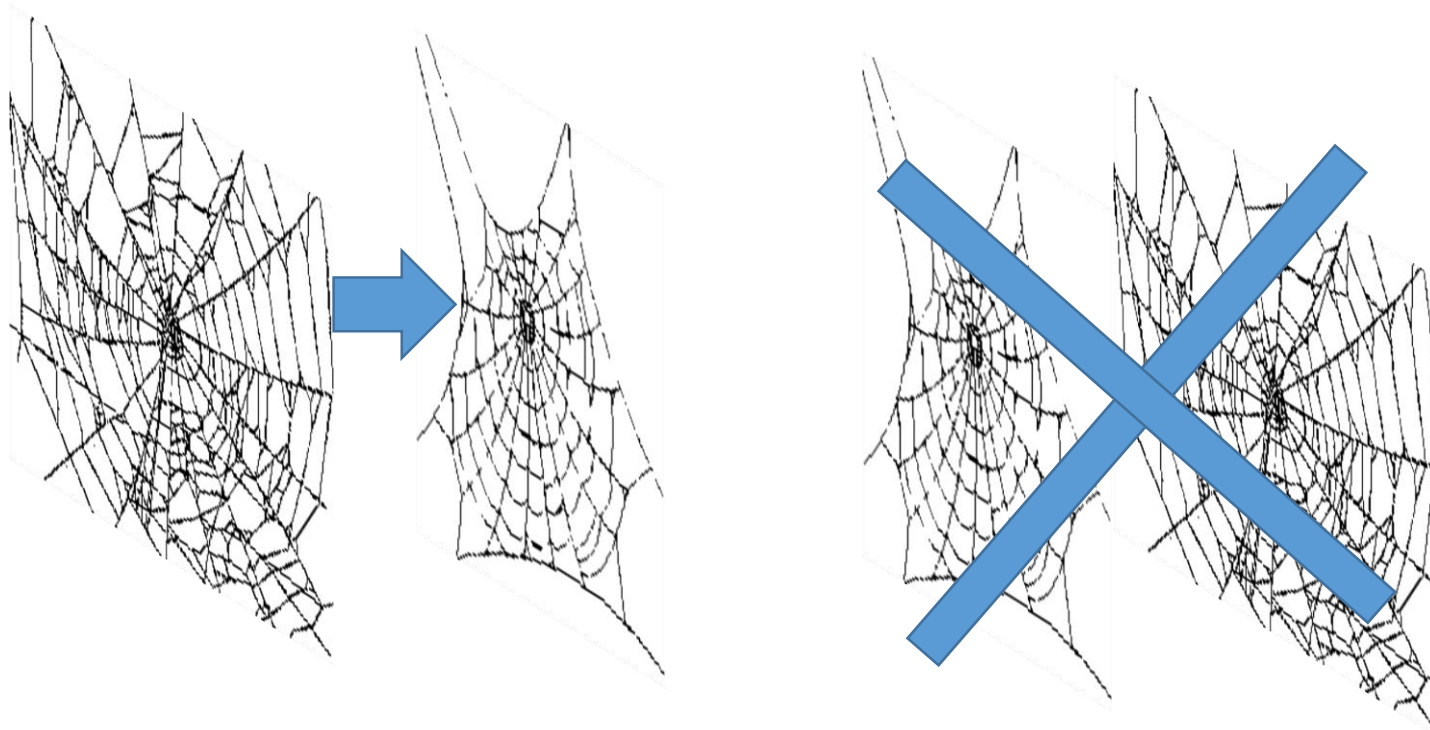
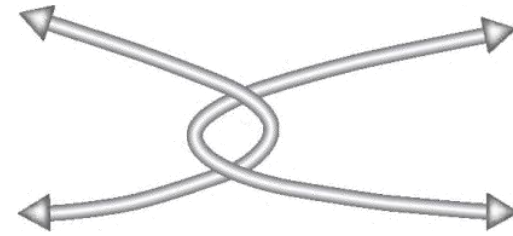
$$\Delta F_{aff} = \frac{kT}{2} \nu V \left(\lambda^2 + \frac{2}{\lambda} - 1 \right) \quad \sigma = kT \nu \left(\lambda - \frac{1}{\lambda^2} \right) \quad \sigma_N = G_x \left(\lambda - \frac{1}{\lambda^2} \right)$$

2. Elastic response is nonlinear.

3. Stress is universal, does not depend on the chemical structure of the chain.

Treloar, L. R. G. (1975). The general strain: phenomenological theory. The physics of rubber elasticity. Oxford, Clarendon Press: 210-310.

Two chains cannot pass through each other - **topological interactions** known as **entanglements** that raise the network modulus



Phenomenological models of entanglements

Free energy is function of deformation invariants

$$I_1 = \lambda_x^2 + \lambda_y^2 + \lambda_z^2, \quad I_2 = \frac{1}{\lambda_x^2} + \frac{1}{\lambda_y^2} + \frac{1}{\lambda_z^2}$$

Mooney—Rivlin model

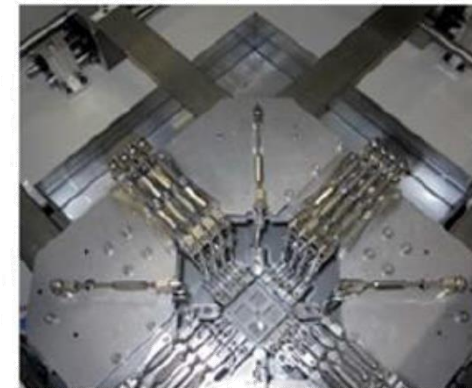
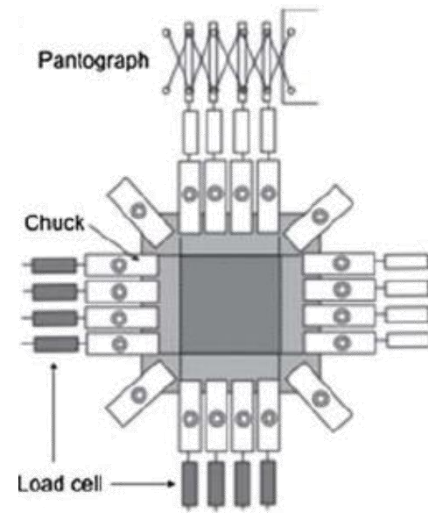
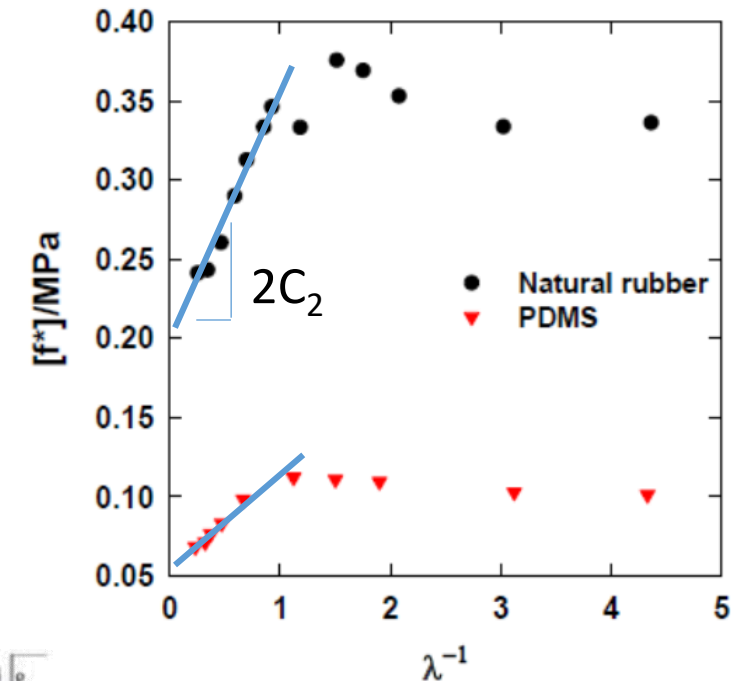
$$\Delta F/V = C_1 (I_1 - 3) + C_2 (I_2 - 3)$$

The stress of **uniaxially** deformed network

$$\sigma = \left(\lambda^2 - \frac{1}{\lambda} \right) f^* (\lambda),$$
$$f^* (\lambda) = 2C_1 + \frac{2C_2}{\lambda}$$

Biaxially stretched gel –
more complex function

$$\Delta F/V = C_1 (I_1 - 3) + f(I_1, I_2)$$



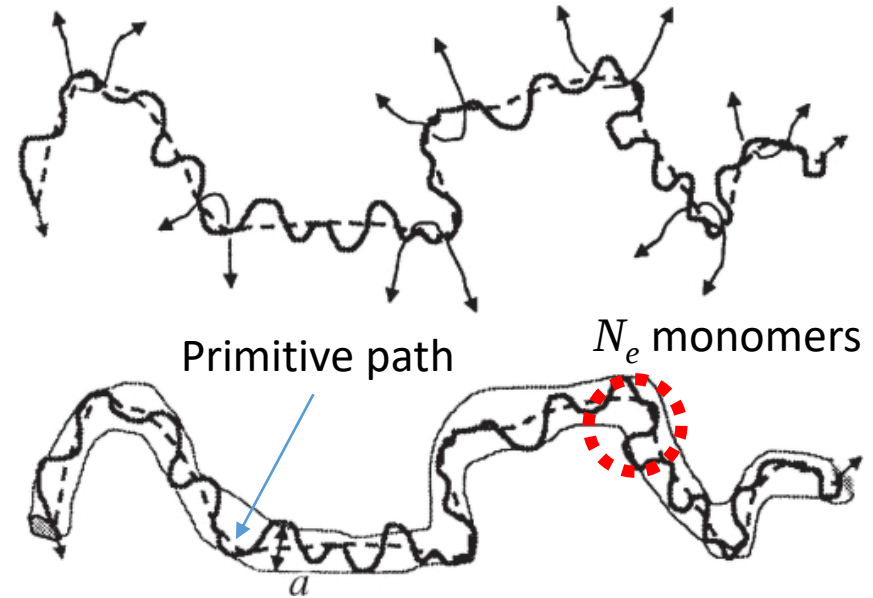
Mooney, M. (1940). "A Theory of Large Elastic Deformation." *Journal of Applied Physics* **11**: 582.

A strand is topologically constrained to a tube-like region by surrounding chains.

Tube diameter $a \simeq bN_e^{1/2}$

Rubber plateau modulus

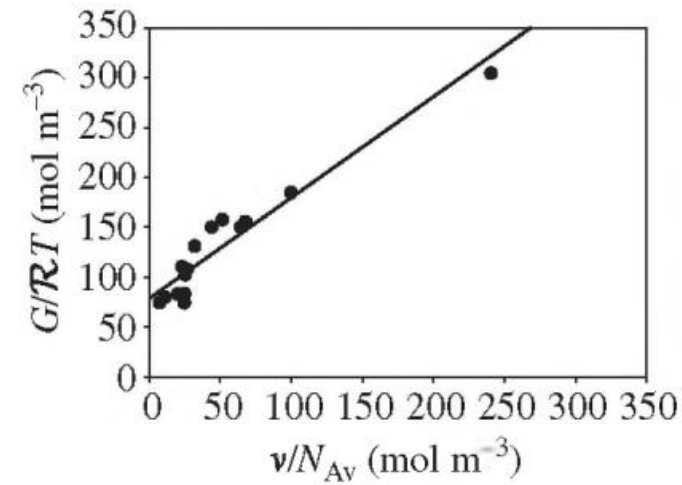
$$G_e = \rho kT / M_e$$



The modulus of the entangled polymer network can be approximated as

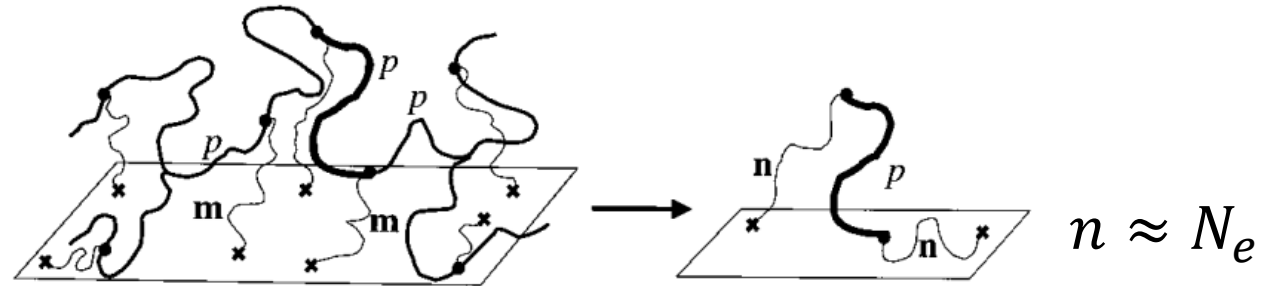
$$G \simeq G_x + G_e \simeq \rho kT \left(\frac{1}{n} + \frac{1}{N_e} \right)$$

Modulus of end-linked PDMS networks
with $f = 4$ at 30°C



Edwards tube model

Every p th monomer of a strand (intermediate and thick lines) is connected to the elastic nonfluctuating background by virtual chains with m monomers



Tube diameter does not depend on deformations

$$a \simeq bN_e^{1/2}$$

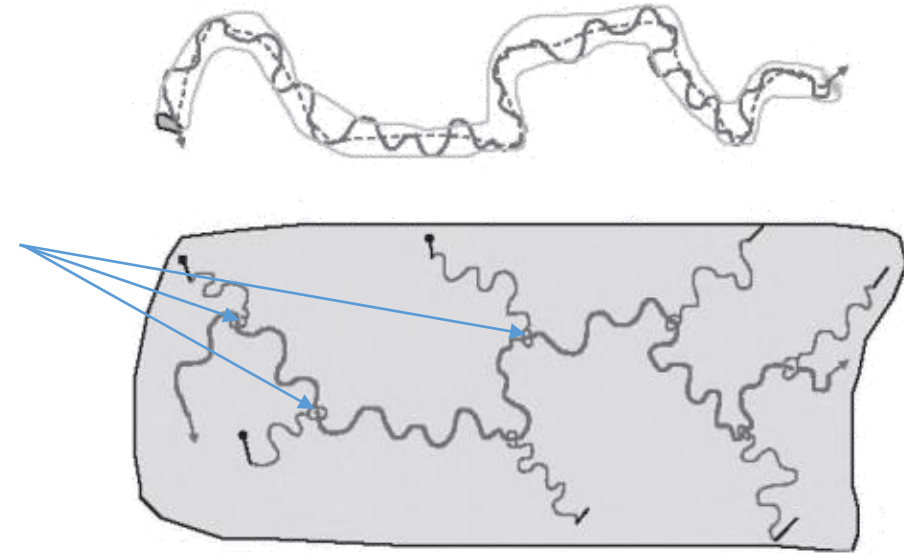
Nonaffine tube model

Tube diameter depends on deformations

$$a_i \simeq bN_e^{1/2} \lambda_i^{1/2}$$

Nonaffine slip-tube model

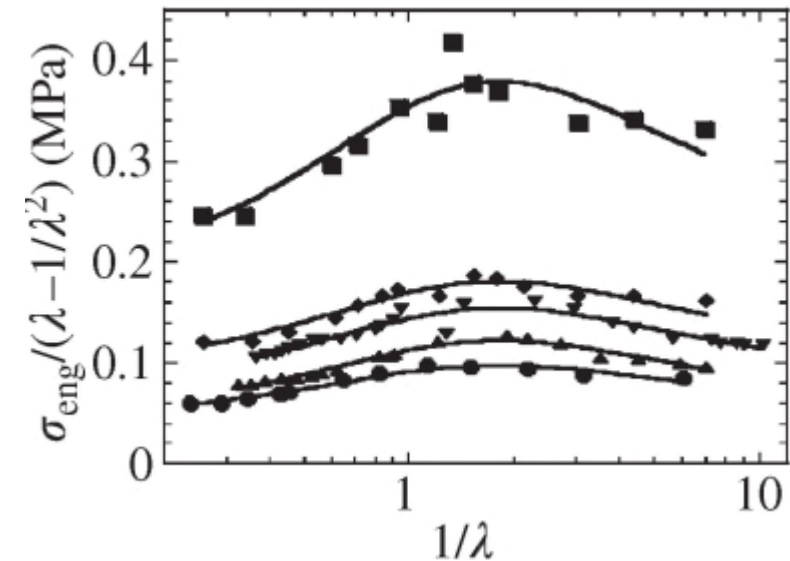
Slip-links can slide along the network chain, but cannot pass through each other.



The stress for uniaxial deformation

$$\frac{\sigma}{\lambda - 1/\lambda^2} = G_x + \frac{G_e}{0.74\lambda + 0.61\lambda^{-1/2} - 0.35}$$

Reduced stress of different rubbers



Rubinstein, M. and S. Panyukov (2002). "Elasticity of polymer networks." *Macromolecules* **35**: 6670-6886.

Finite extensibility

Deviations at large λ

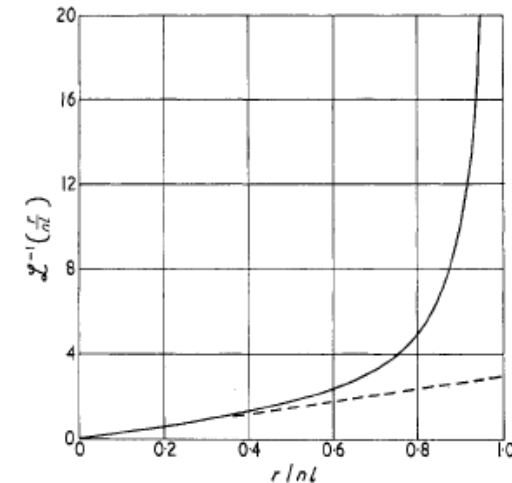
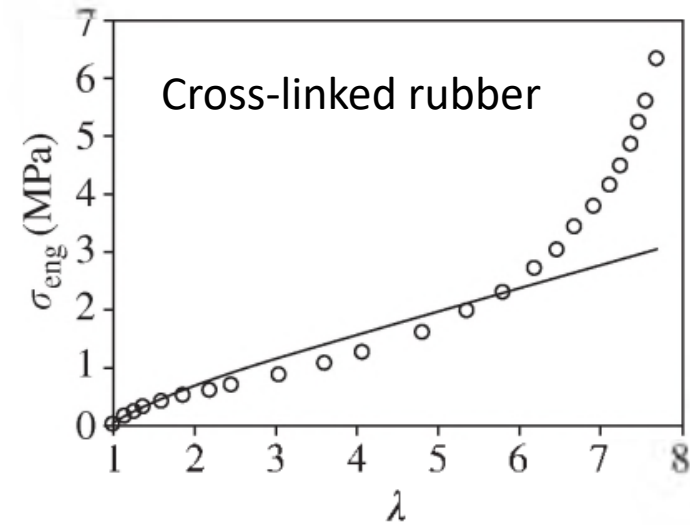
Strain hardening at high deformations λ can be explained by the non-Gaussian statistics of strongly deformed chains:

$$\frac{R}{bn} = \mathcal{L} \left(\frac{fb}{kT} \right) = \coth \frac{fb}{kT} - \frac{kT}{fb}$$

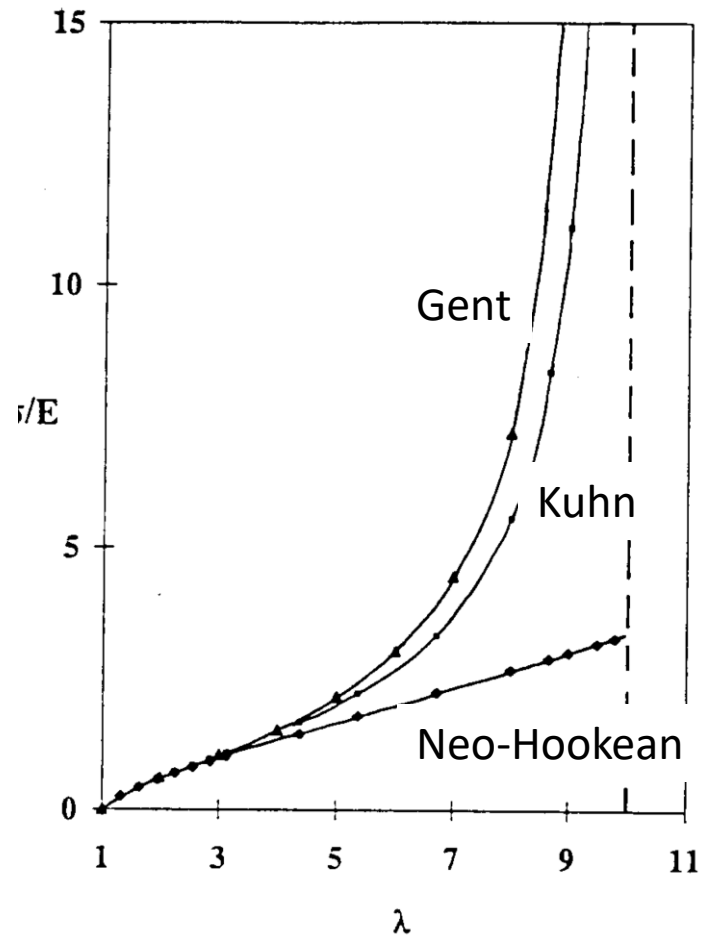
The force f required to stretch a single chain to an end-to-end distance X can be expressed through the inverse Langevin function:

$$f = \frac{kT}{b} \mathcal{L}^{-1} \left(\frac{R}{bn} \right)$$

This is still entropic but no longer Gaussian



Macroscopic phenomenological 3D model



$$W = -\frac{G_x}{2} J_m \ln \left(1 - \frac{J_1}{J_m} \right)$$

$$J_1 = \lambda_1^2 + \lambda_2^2 + \lambda_3^2 - 3$$

In uniaxial extension

$$\sigma_N = G_x \left(\frac{\lambda - \frac{1}{\lambda^2}}{1 - \frac{J_1}{J_m}} \right)$$

2 parameters: G_x and J_m

*Gent, A. N. (1996). "A New constitutive relation for rubber." Rubber Chemistry and Technology **69**: 59-61.*

Testing methods

Small strain: elastic modulus, linear viscoelastic properties (lecture of Hiroshi Watanabe)

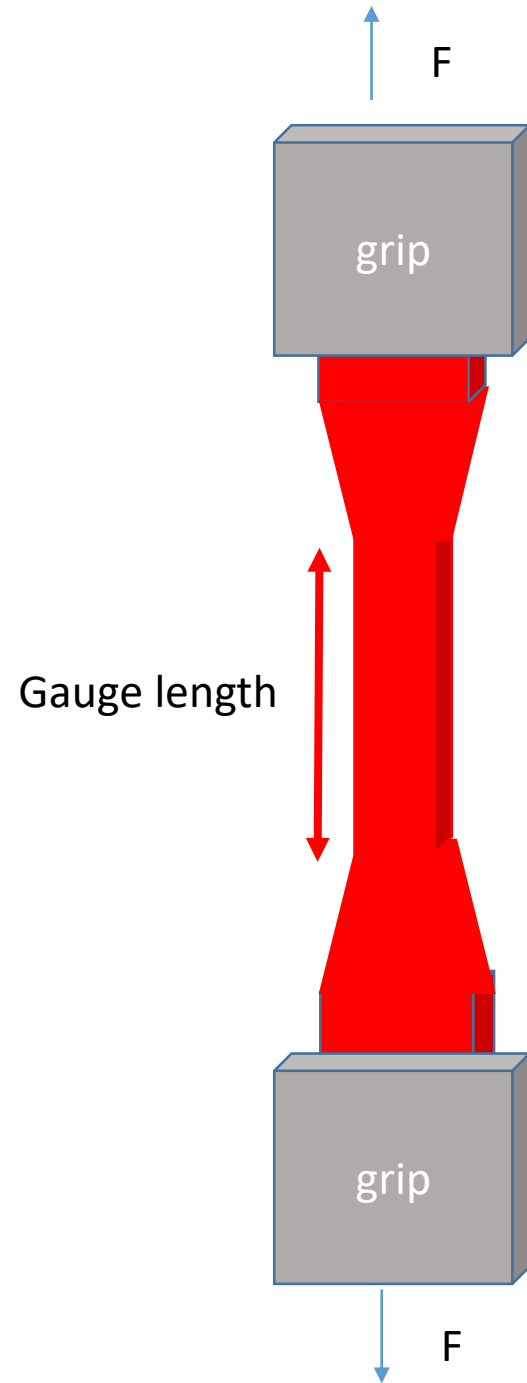
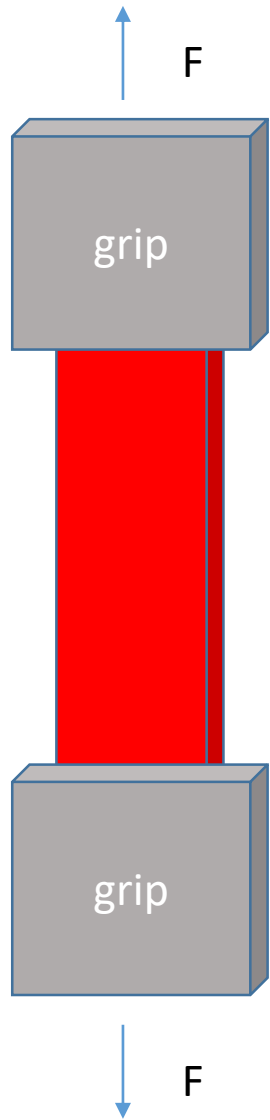
Large strain: Uniaxial, pure shear, biaxial, uniaxial compression

Boundary conditions: material properties need to be tested in homogeneous deformation

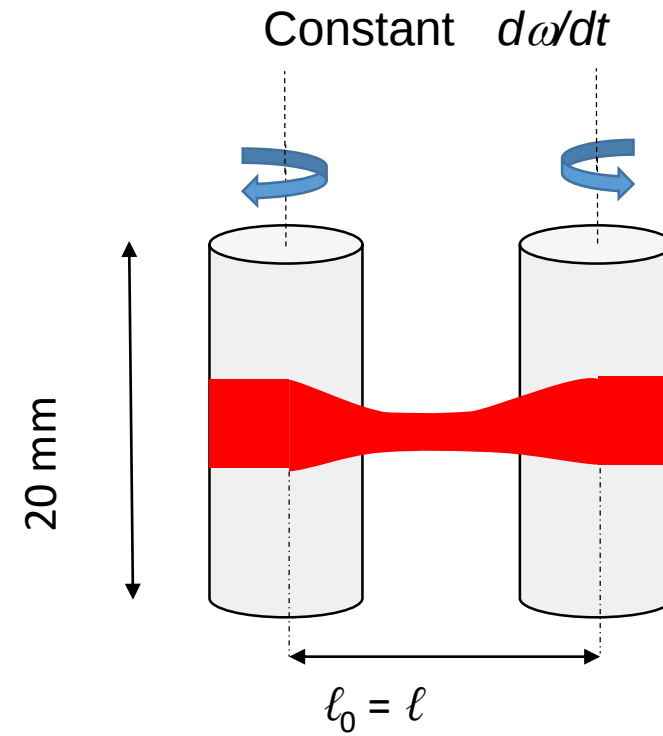
Mechanical testing with heterogeneous deformation

Fracture tests: experimental aspects and interpretations (DIC, strain field, Crack tip structure)

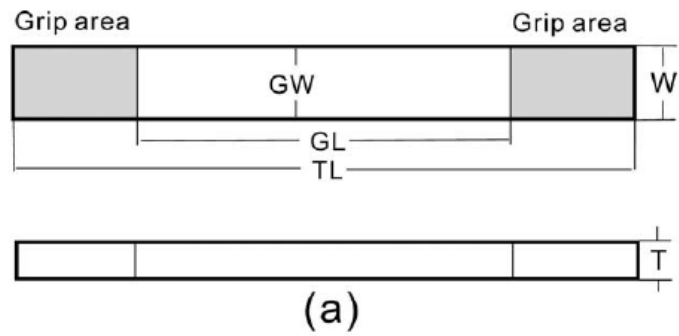
Sticky thin films: how to test adhesion



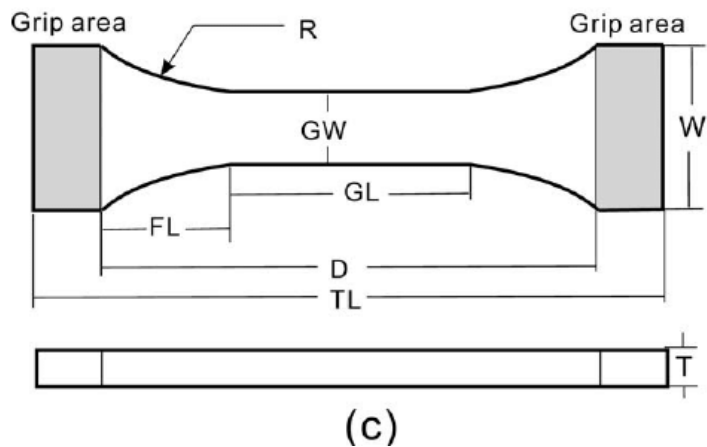
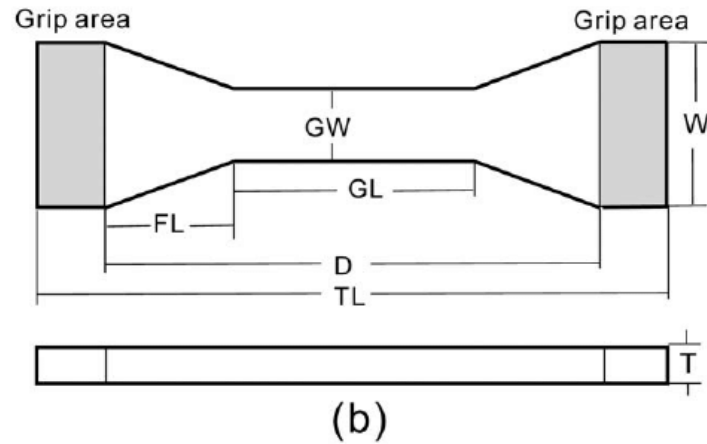
Tensile tests: practical aspects

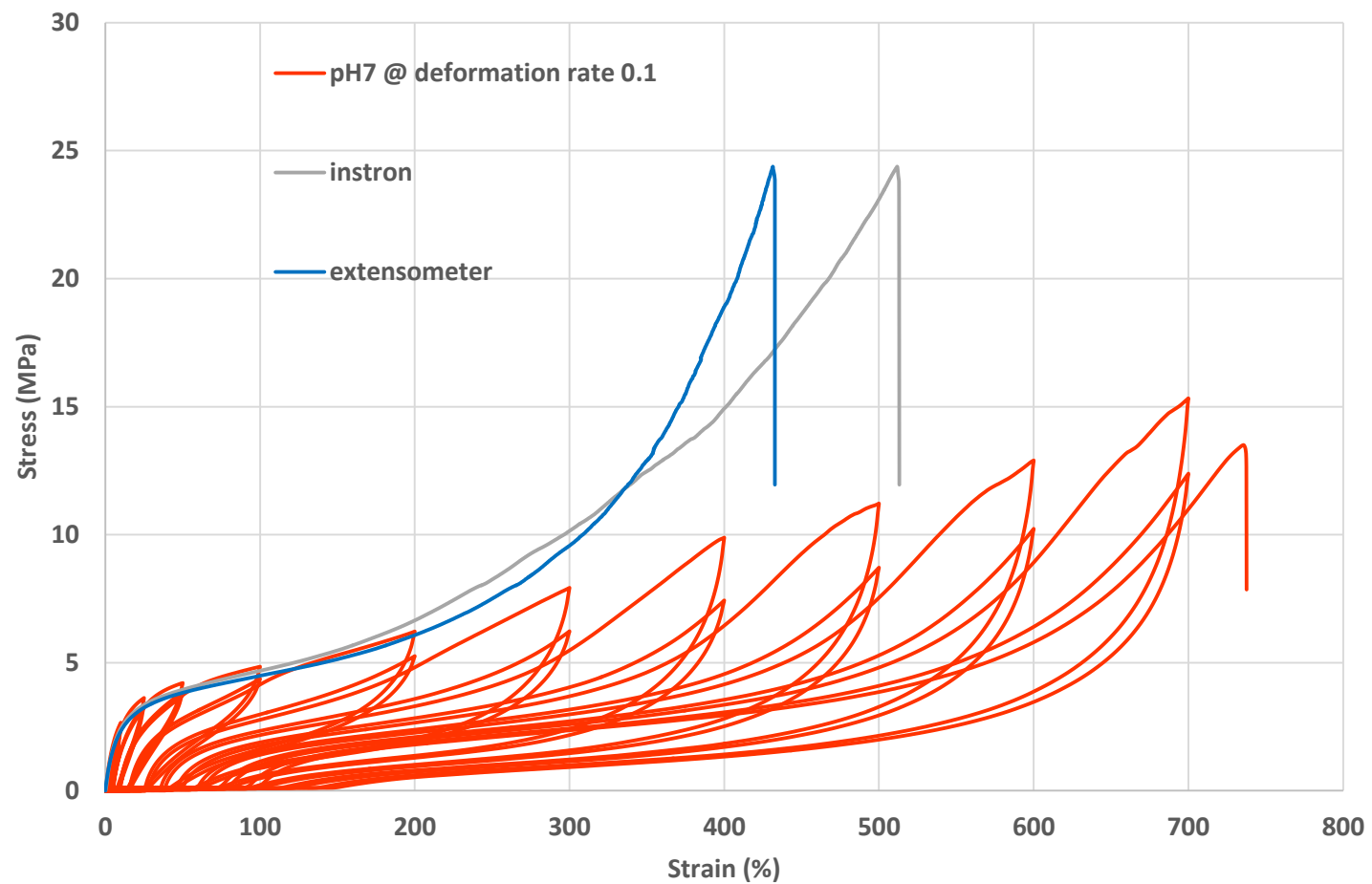
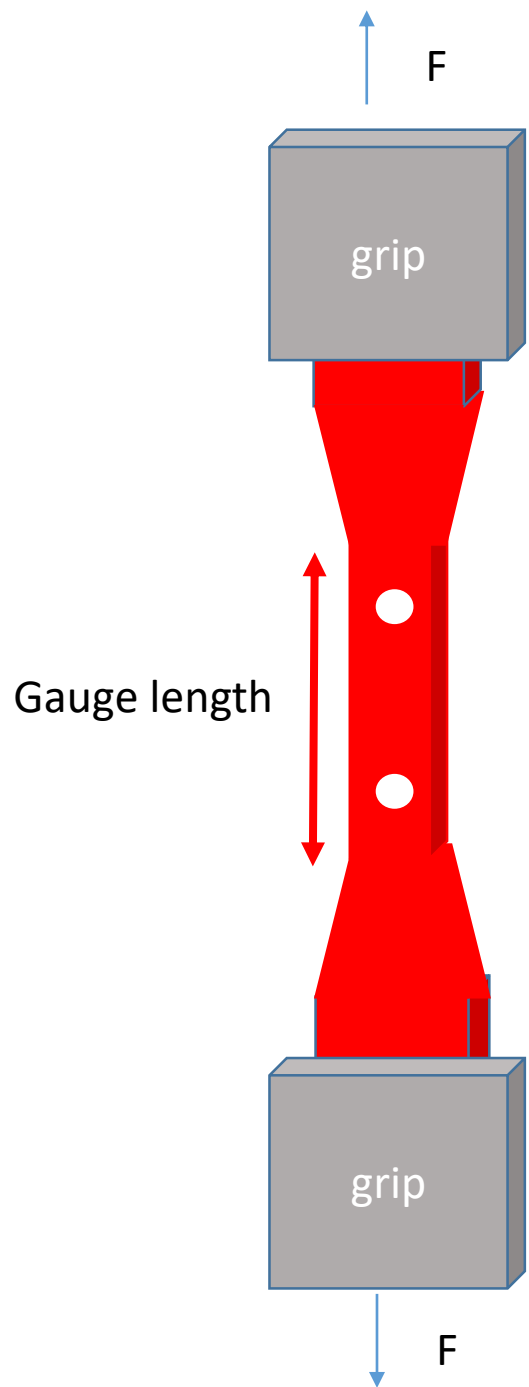


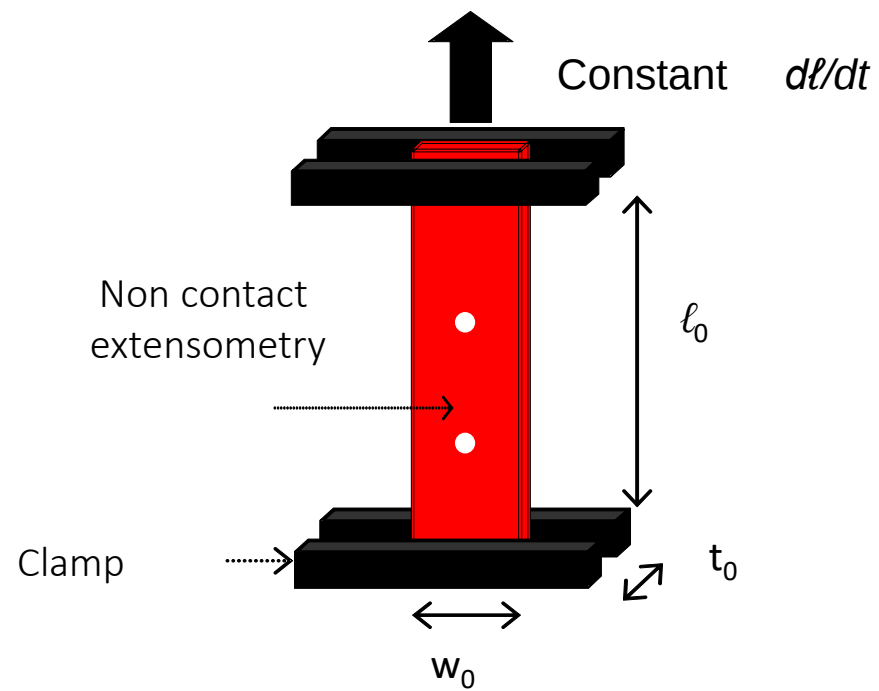
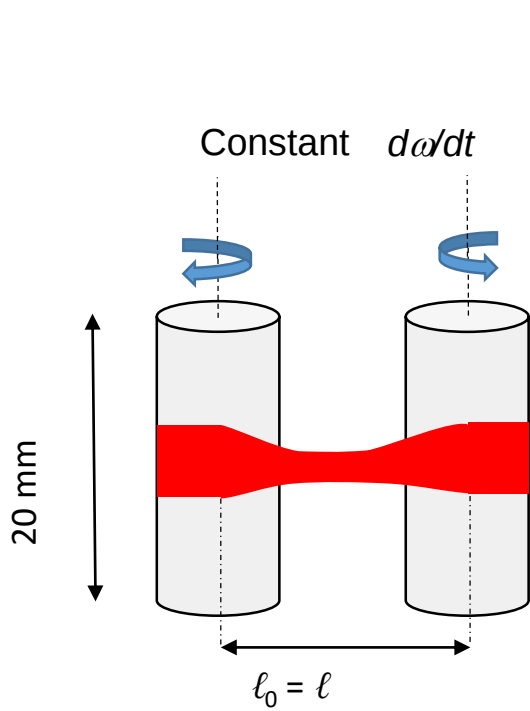
Sentmanat, M. L.,
Rheologica Acta **2004**, *43* (6), 657-669.



Stress
concentration

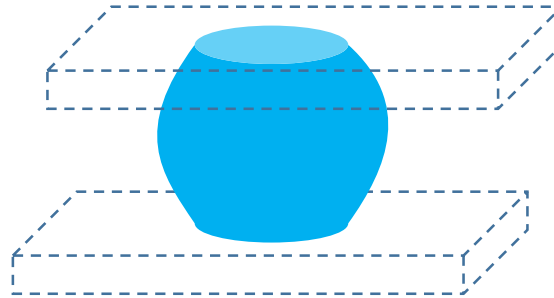
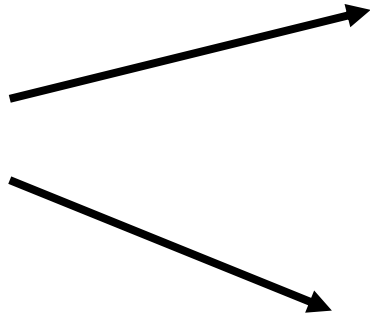
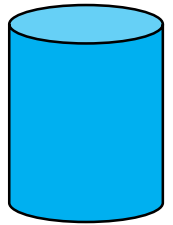
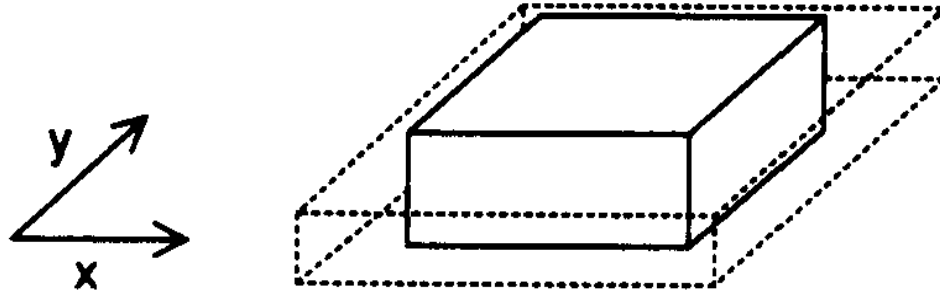




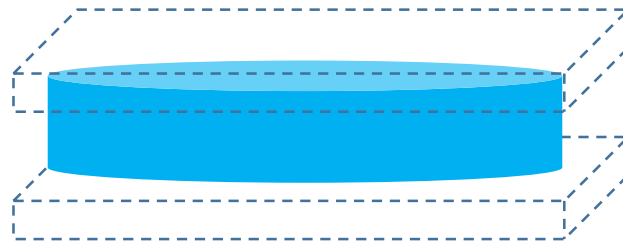


In viscoelastic materials, strain rate history matters

Compression tests: boundary conditions



Sticky wall ($\beta = 0$)



Slippery wall ($\beta = \infty$)

$$v_s(r, h) = \beta \tau_{zr}(r, h)$$
$$E_{sq} = 3G \left[1 + \frac{1}{2(H/R)^2(1 + 5\beta G/H)} \right].$$

Nominal stress – True Stress

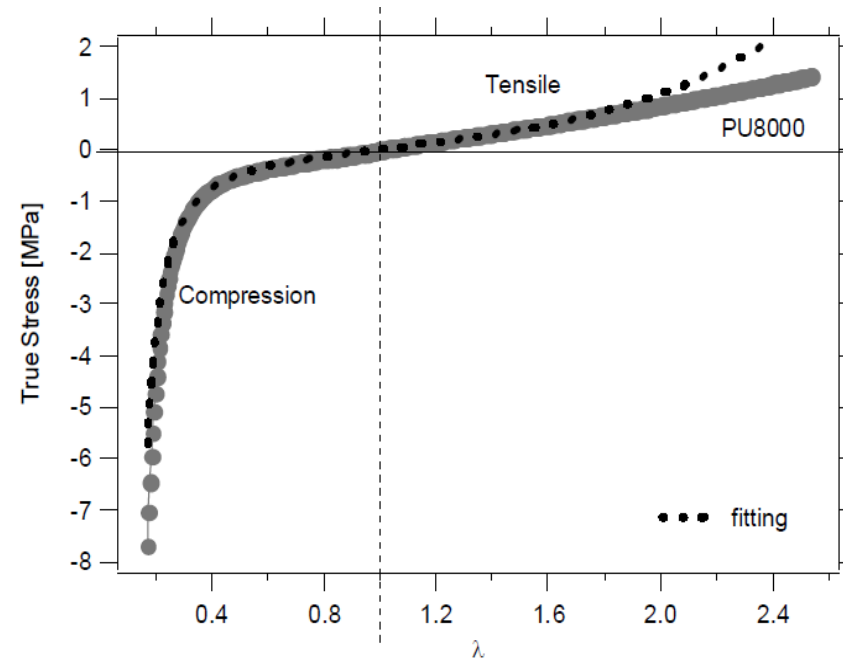
$$\sigma_N = \frac{F}{A_0}$$

Constant volume

$$\sigma_T = \frac{F}{A}$$

$$\frac{A}{A_0} = \frac{\ell_0}{\ell} = \frac{1}{\lambda}$$

$$\sigma_T = \lambda \sigma_N$$



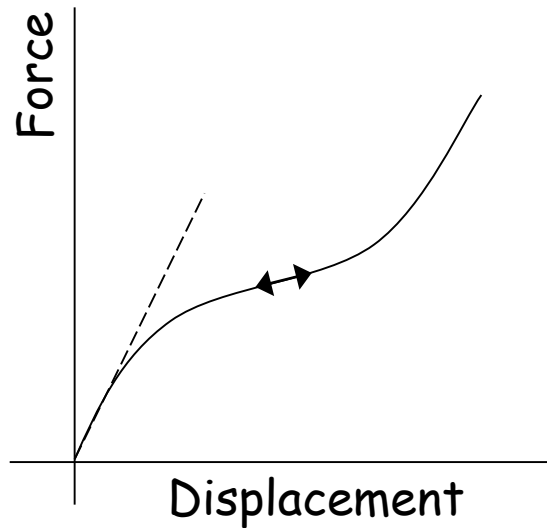
In tension: $|\sigma_T| \gg |\sigma_N|$

In compression: $|\sigma_T| \ll |\sigma_N|$

Some definitions

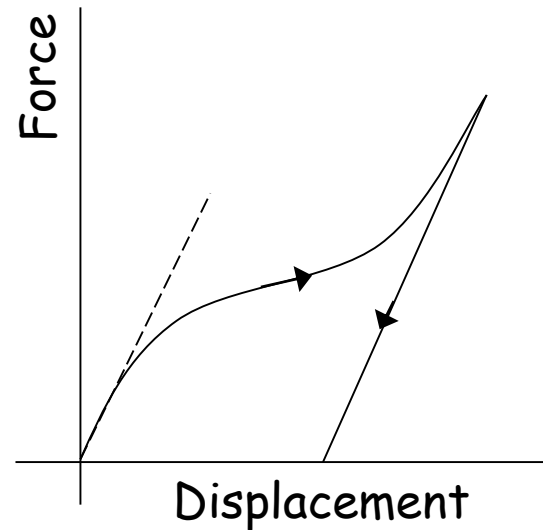


Elasticity



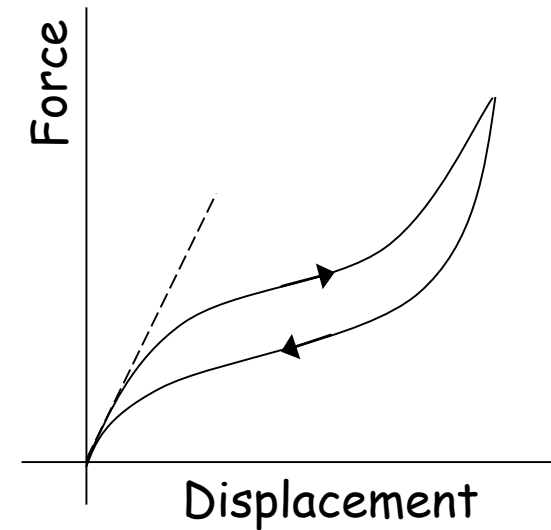
reversible deformation,
dissipates no energy

Plasticity, Damage



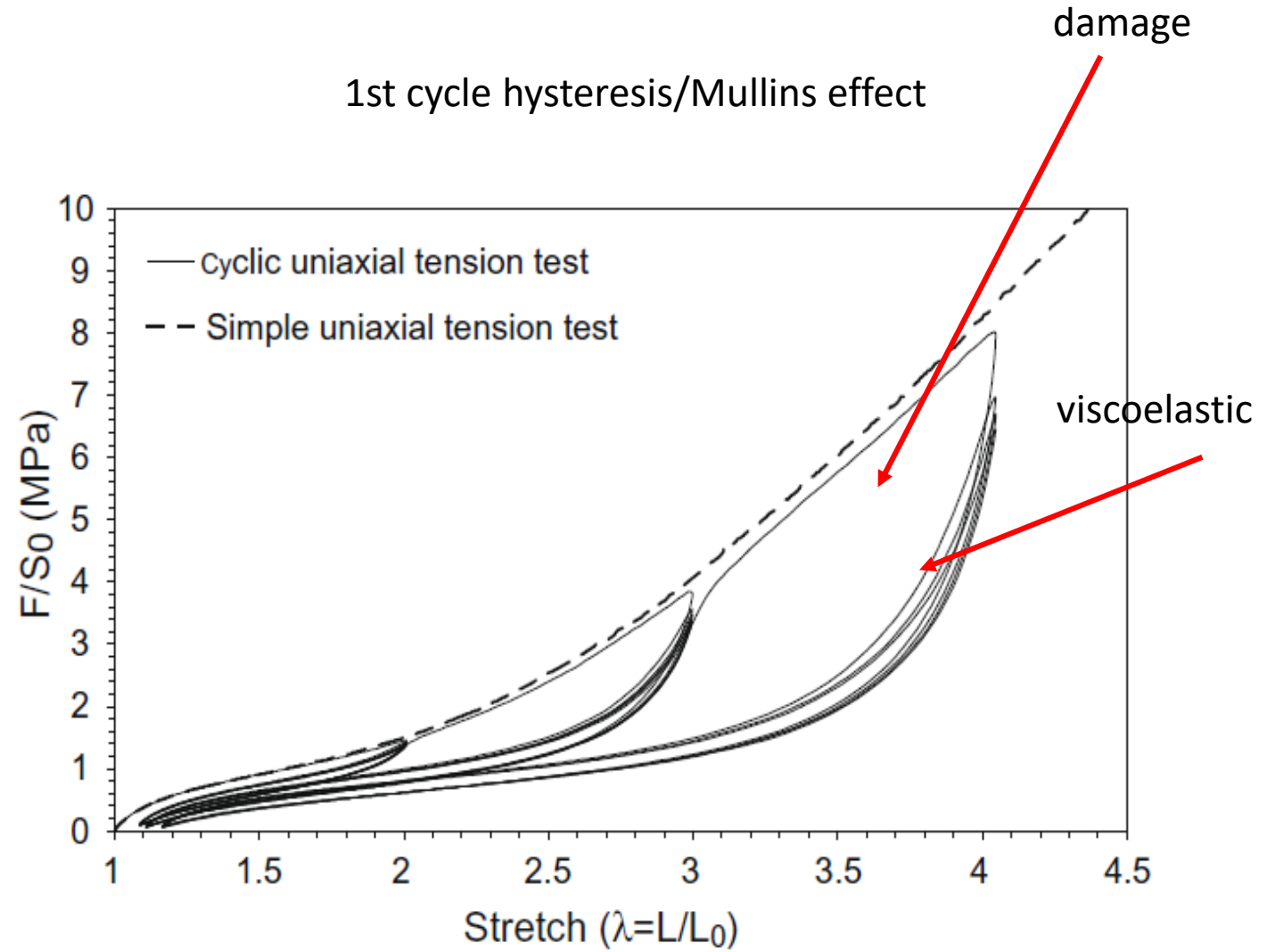
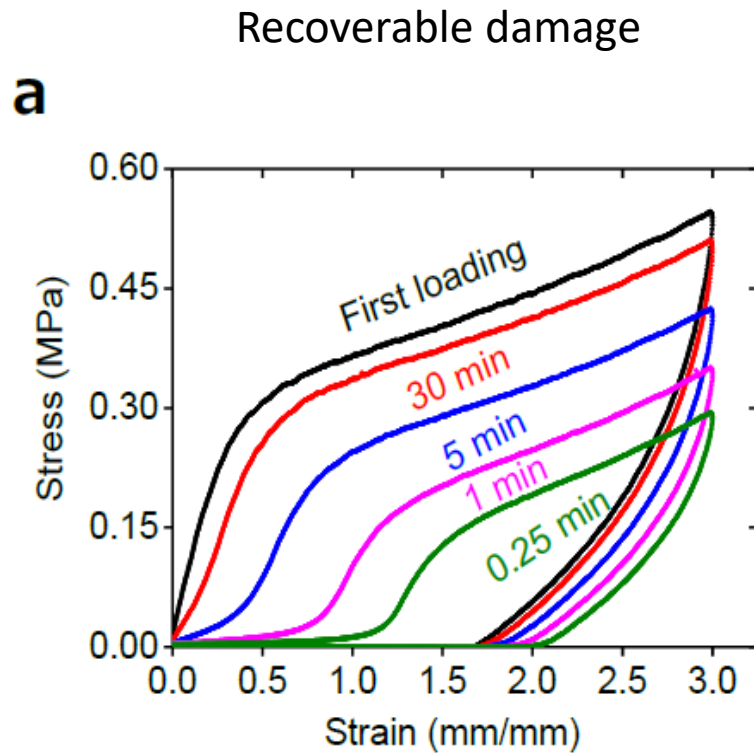
irreversible
deformation, dissipates
energy

Viscoelasticity



dissipates energy

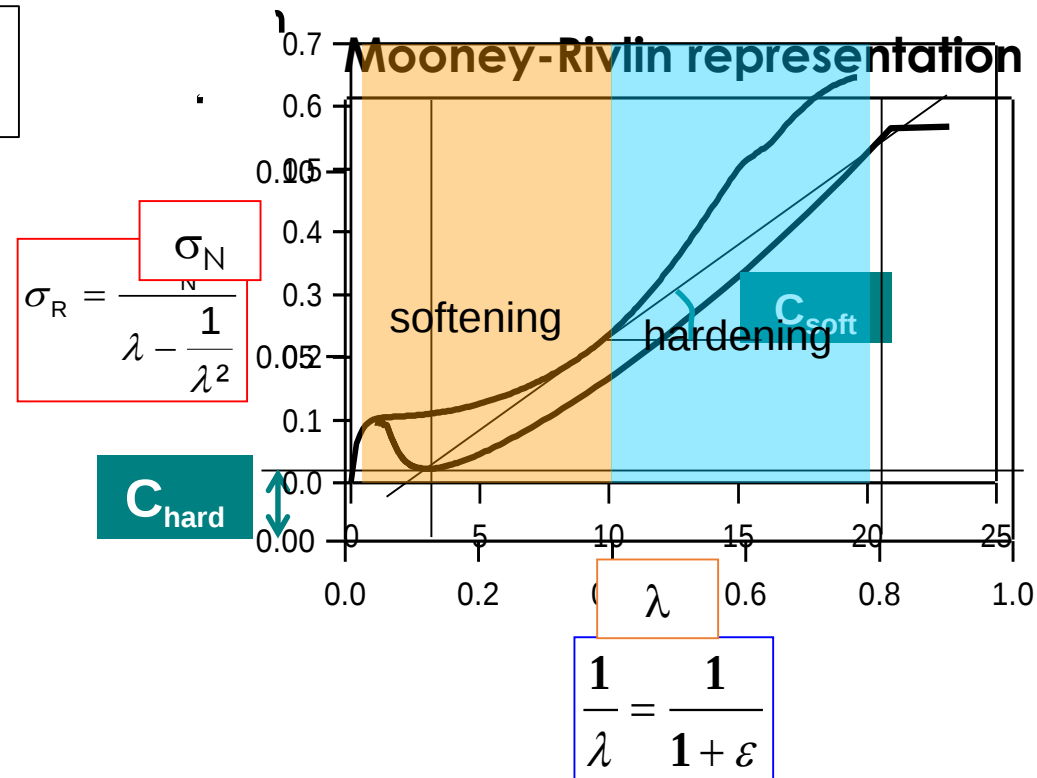
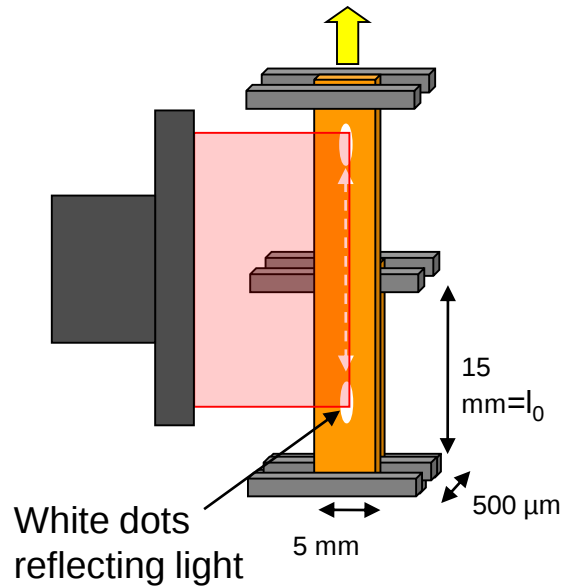
More complex behavior



Change/breakage of internal structure

Interpretation of the tensile test for complex behavior

Room temperature
Nominal deformation rate = 1 s^{-1}



softening at intermediate strain $\Leftrightarrow$ role of entanglements $\rightarrow C_{\text{soft}}$

hardening at large strain $\Leftrightarrow$ role of crosslinking points $\rightarrow C_{\text{hard}}$

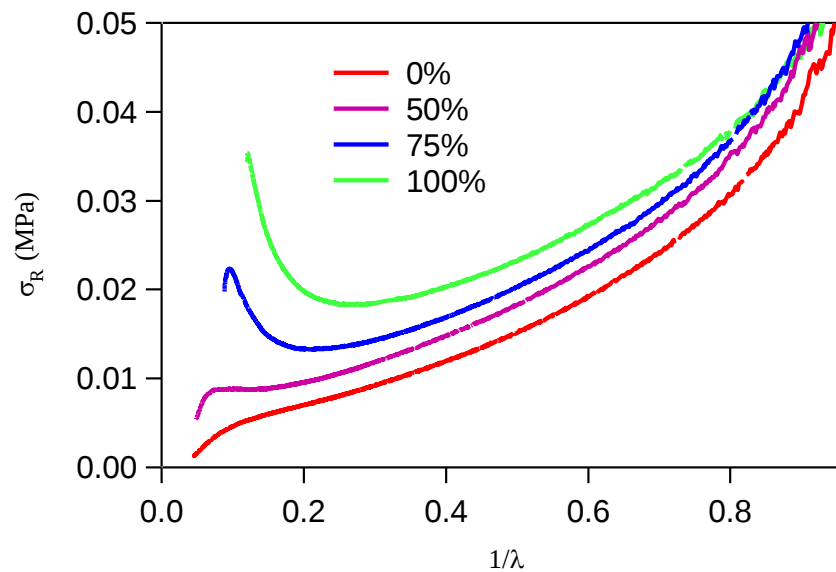
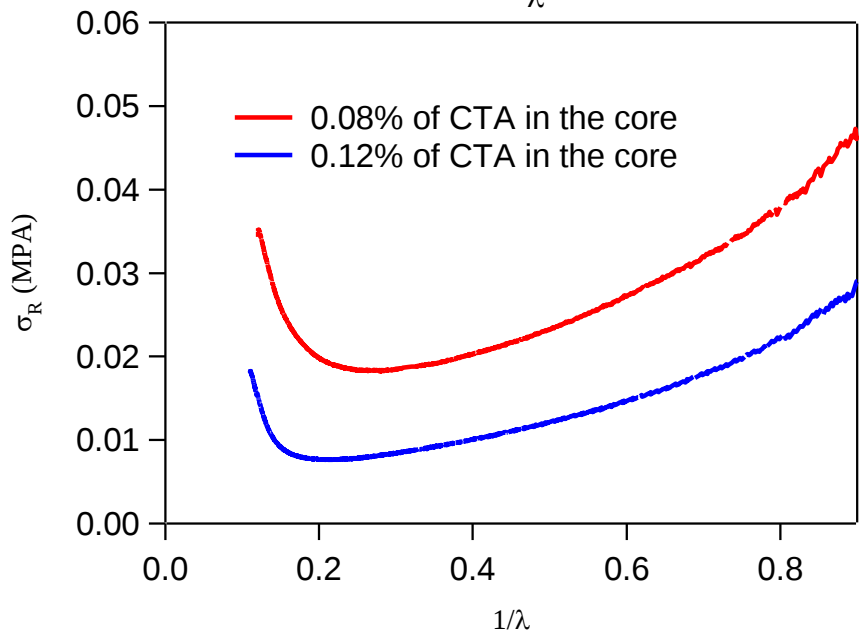
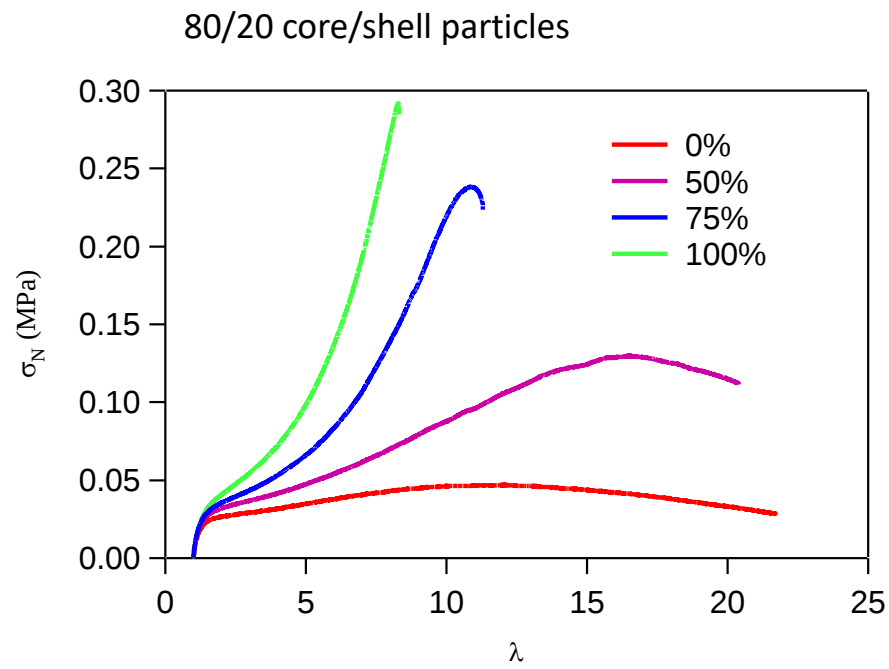
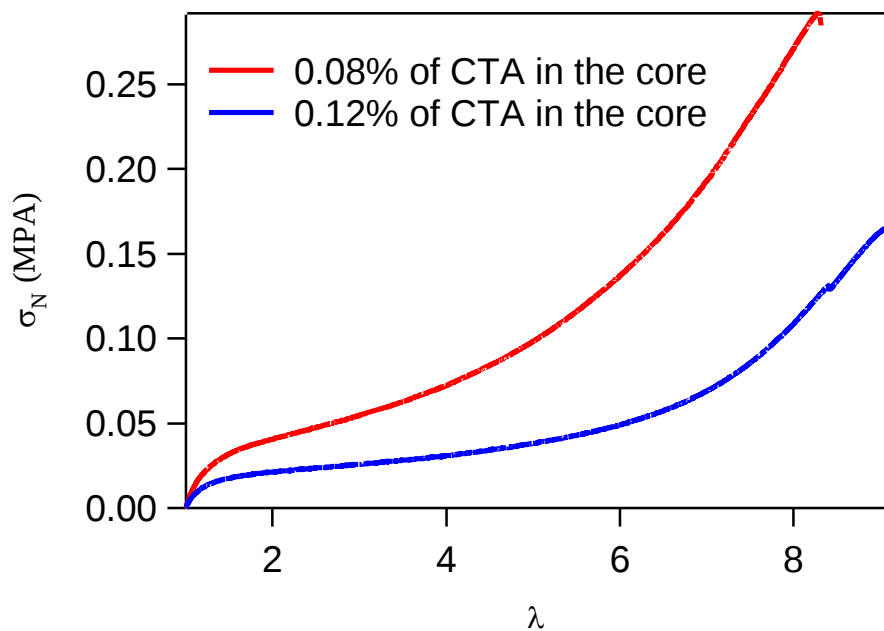
$\rightarrow C_{\text{hard}}$

$\xrightarrow{\epsilon \rightarrow 0} \mu_e$

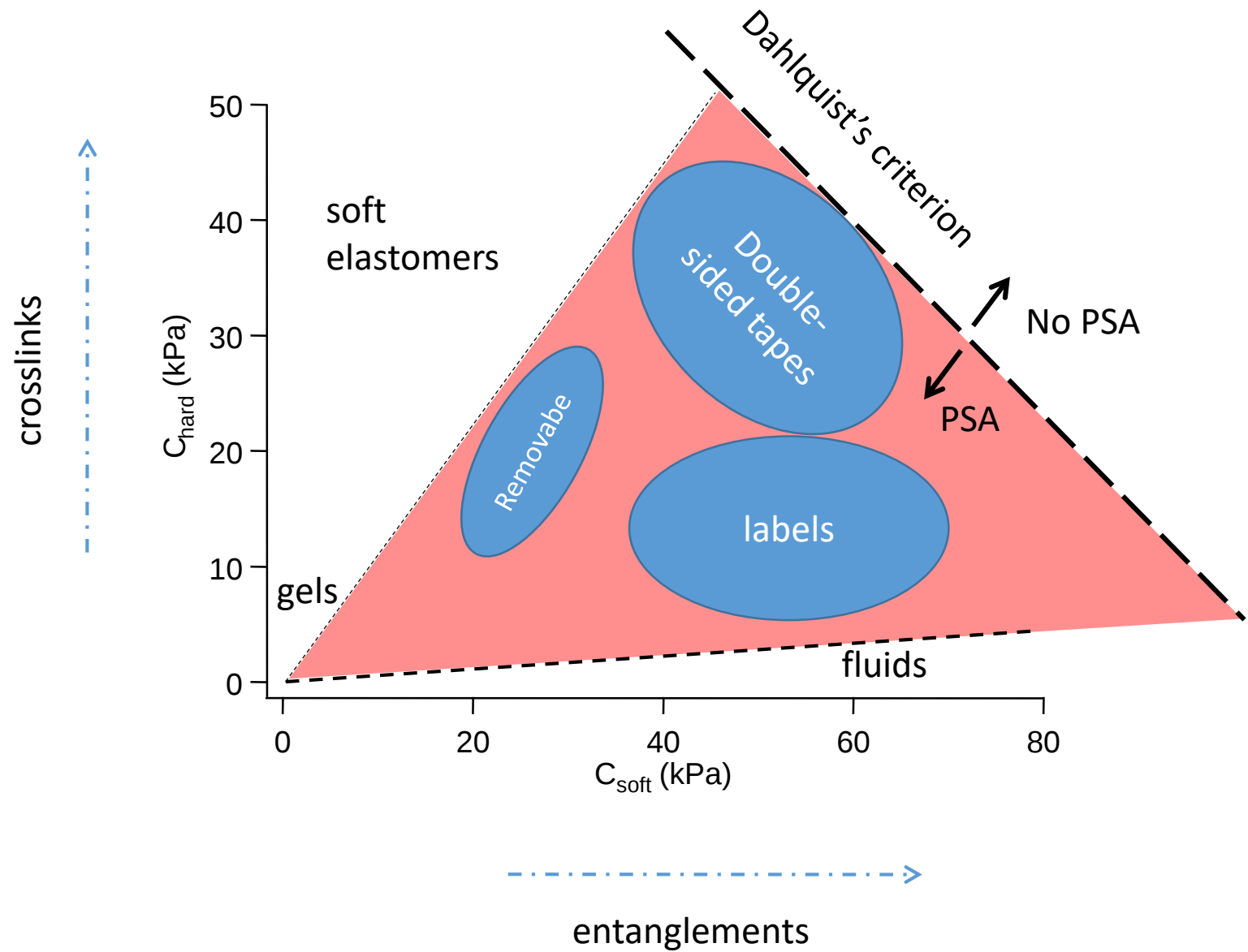
$\rightarrow \mu_x$

$C_{\text{soft}}/C_{\text{hard}}$: viscoelastic properties at large strain

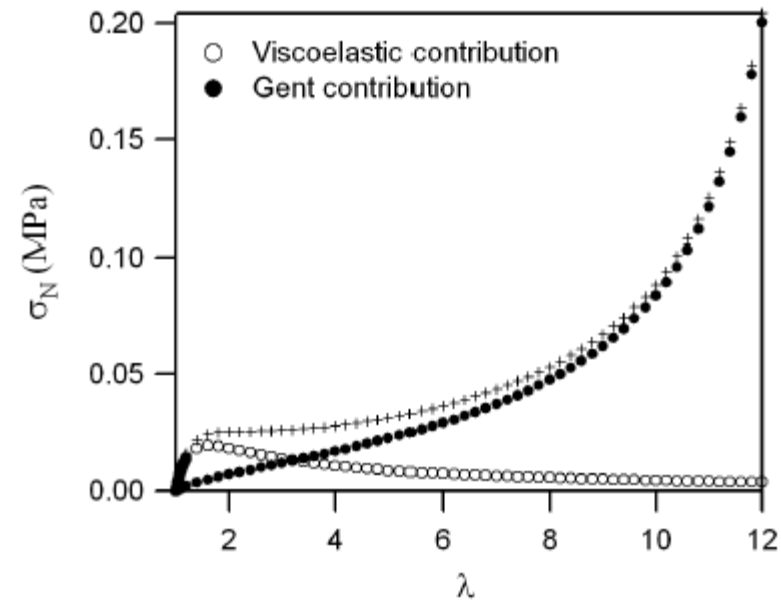
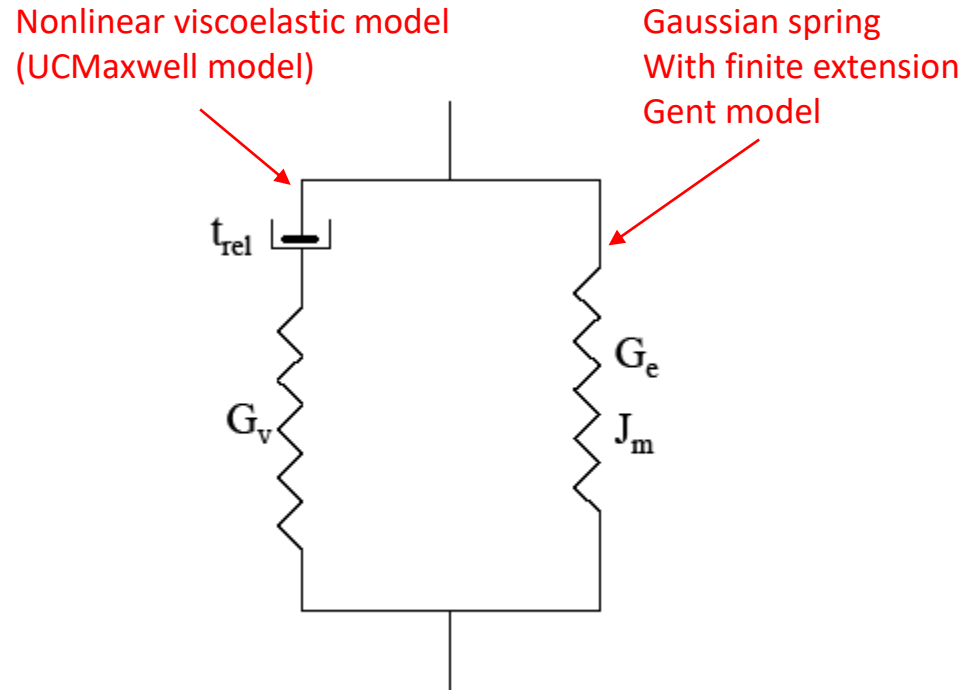
$C_{\text{soft}} + C_{\text{hard}}$: elastic modulus at small strain



Mooney plots

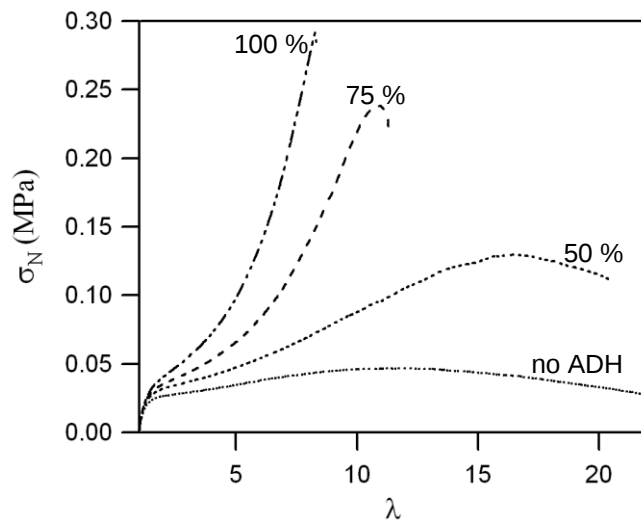


Some simple modeling of large strain properties combining dissipation and strain hardening



Deplace, F.; Rabjohns, M. A.; Yamaguchi, T.; Foster, A. B.; Carelli, C.; Lei, C. H.; Ouzineb, K.; Keddie, J. L.; Lovell, P. A.; Creton, C. *Soft Matter* **2009**, *5*, 1440-1447.

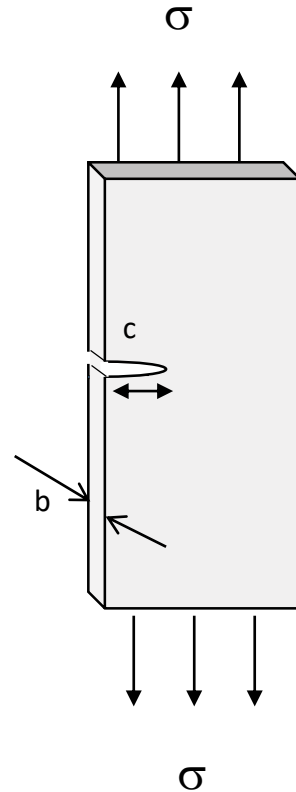
Effect of xlinking in films made from core-shell latex particles



C80d0.1S20 D0.4	G_v (kPa)	G_e (kPa)	J_m	De	G_v/G_e	$3(G_e+G_v)$ (kPa)
no ADH	30.6 ($\pm$ 2.11)	4.20 ($\pm$ 0.398)	10^6 impose d ^a	0.382 ($\pm$ 0.052)	7.30 ($\pm$ 0.284)	104 ($\pm$ 7.47)
50% ADH	47.4 ($\pm$ 9.73)	7.76 ($\pm$ 0.946)	3170 ($\pm$ 748)	0.211 ($\pm$ 0.068)	6.07 ($\pm$ 0.581)	165 ($\pm$ 31.9)
75% ADH	59.6 ($\pm$ 6.96)	11.9 ($\pm$ 1.01)	211 ($\pm$ 21.5)	0.126 ($\pm$ 0.030)	5.02 ($\pm$ 0.322)	215 ($\pm$ 23.5)
100% ADH	58.8 ($\pm$ 4.01)	16.0 ($\pm$ 0.507)	111 ($\pm$ 4.60)	0.114 ($\pm$ 0.021)	3.68 ($\pm$ 0.204)	224 ($\pm$ 13.0)

*The interfacial crosslinks cause strain hardening , increased G_e and only
A factor of 2 increase in initial modulus*

Fracture of brittle materials: a little bit of mechanics



The crack propagates when

$$\mathcal{G} = \frac{1}{b} \left(\frac{dW}{dc} - \frac{dU_{el}}{dc} \right) = \Gamma$$

Or when the local stress is higher than the bond breakage stress

$$\sigma_{loc} \approx \frac{K}{\sqrt{\chi}}$$

$$K \approx \sqrt{\mathcal{G}E}$$

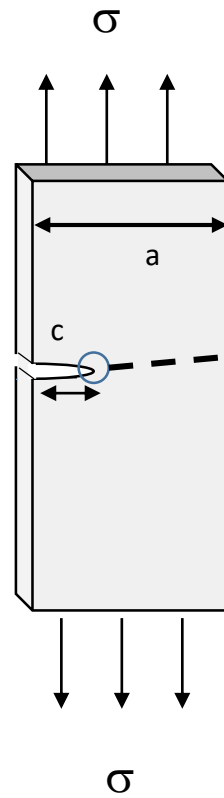
K and $\mathcal{G}$ depend on loading, elastic modulus and geometry

Γ is the dissipated energy

Separation of scales: dissipation zone size $\ll$ all relevant dimensions

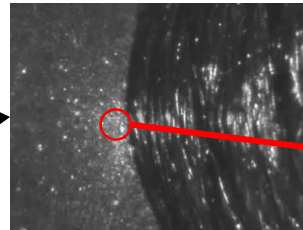
Multi-scale approach of fracture of polymer networks

Macroscopic
scale (mm)



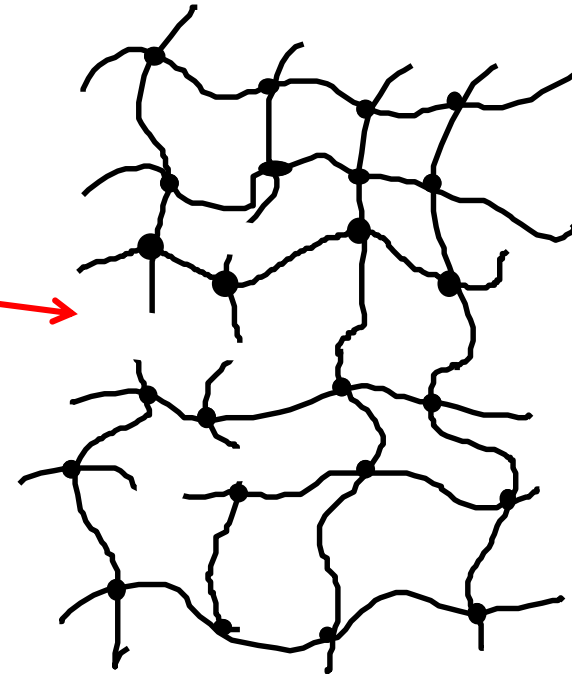
Mechanics :
fracture energy

Intermediate scale
(10-100 μm)



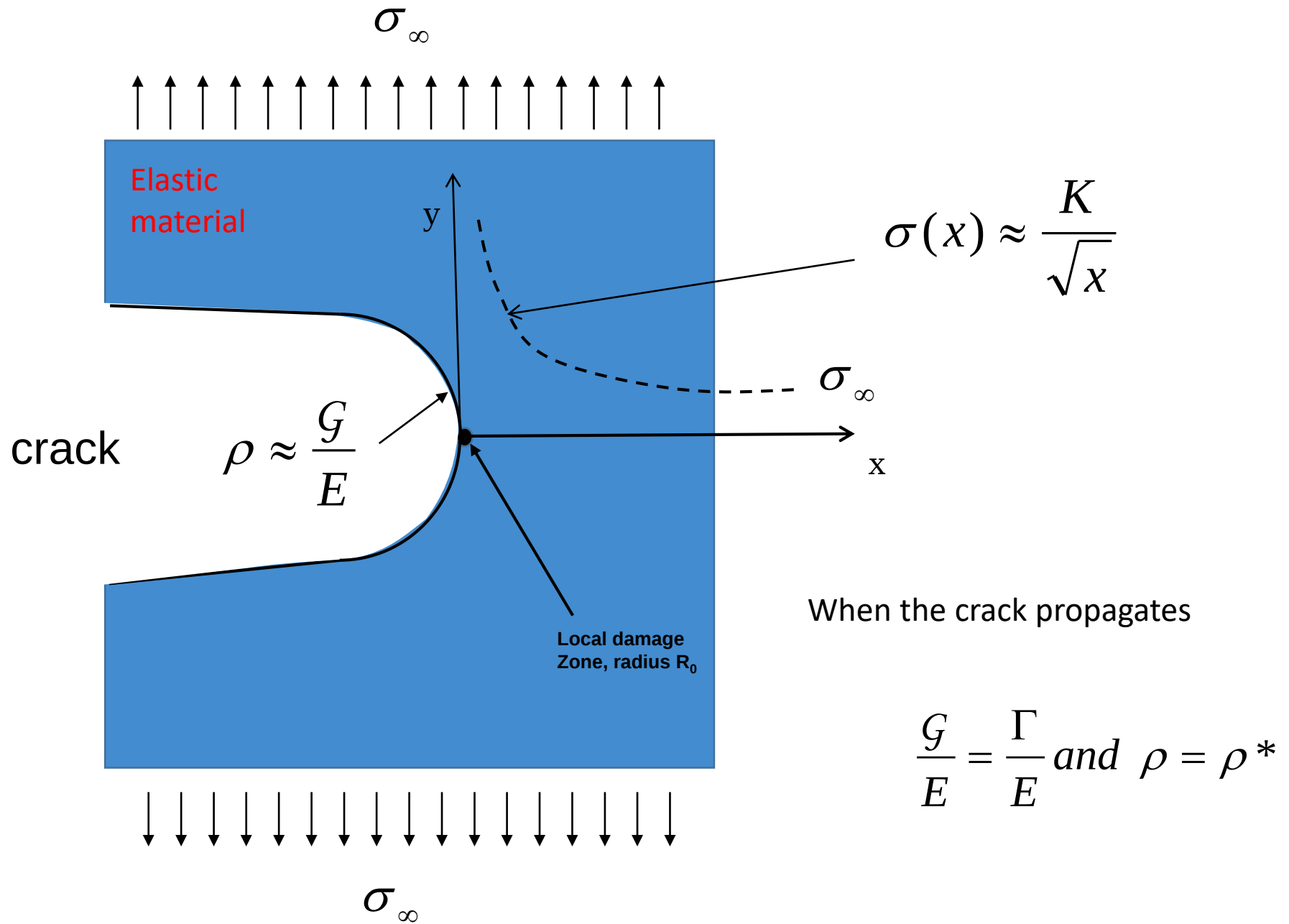
Polymer Physics:
*Cavitation,
Fibril formation
molecular friction*

Molecular scale (nm)



Polymer Chemistry:
Bond breaking

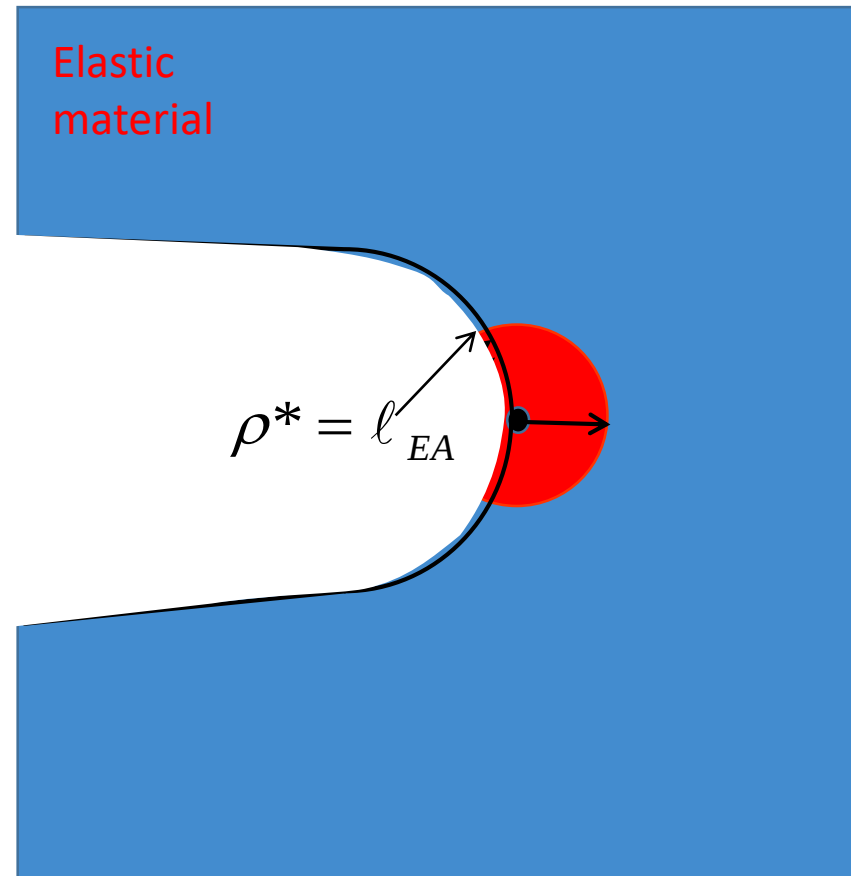
Experiment $\longleftrightarrow$ Theory



$$\frac{\Gamma}{E} = \ell_{EA}$$

Elasto-adhesive length

Surface effects $\sim$ bulk energy density

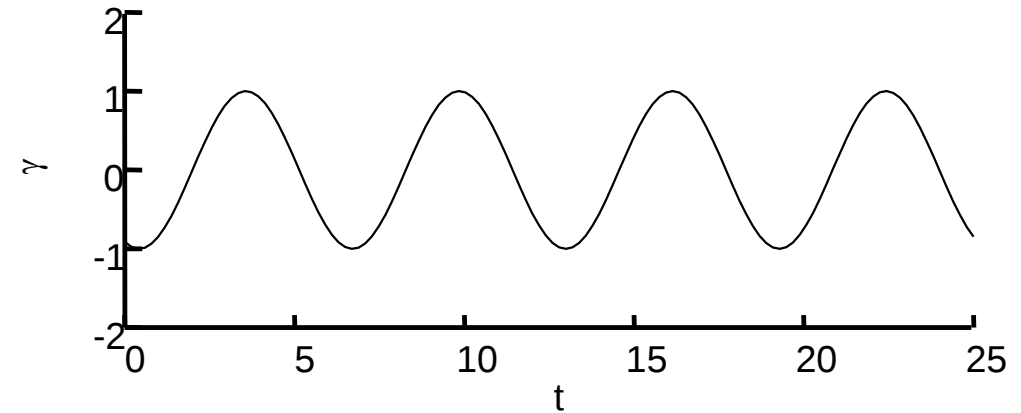
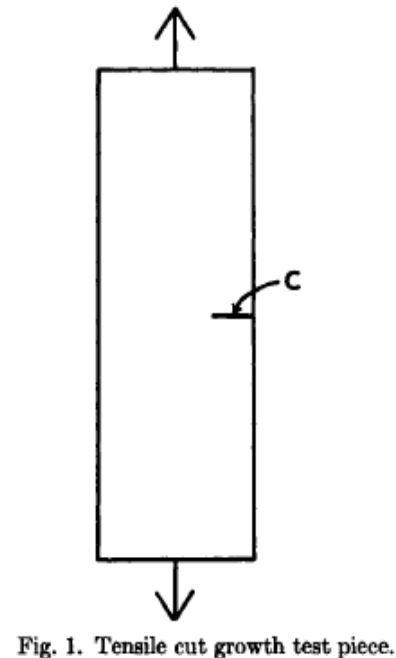
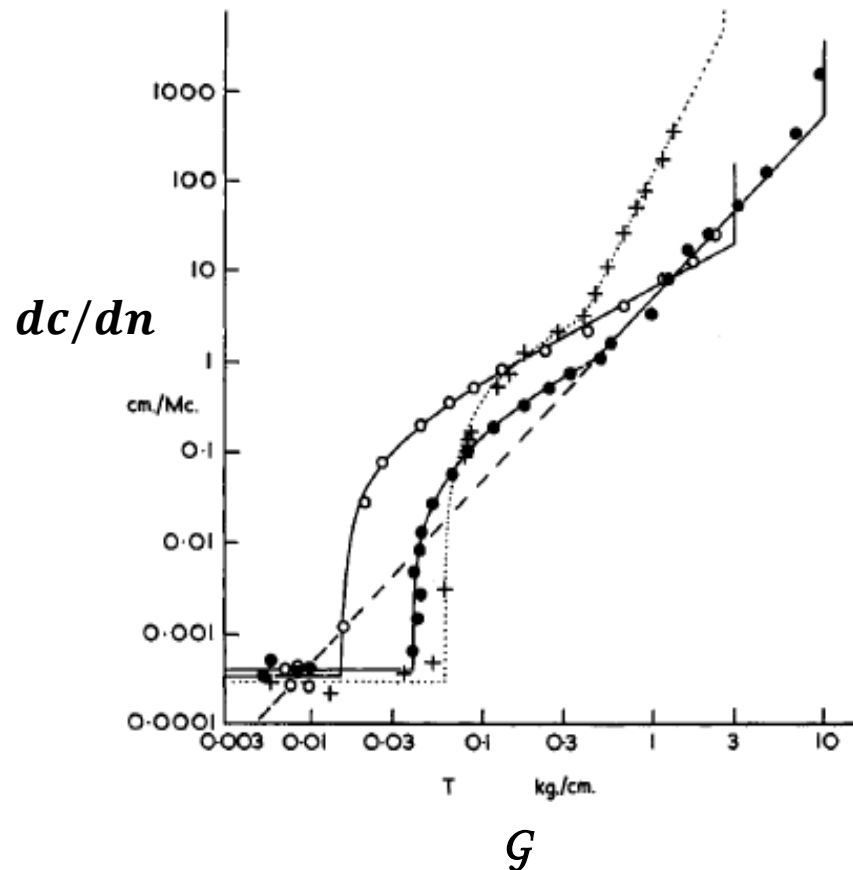


Elastic
material

Material property if the
Dissipative zone remains
Much smaller than ℓ_{EA}

The Mechanical Fatigue Limit for Rubber

G. J. LAKE and P. B. LINDLEY, *The Natural Rubber Producers' Research Association, Welwyn Garden City, Herts., England*



Threshold value in fatigue

Relatively independent of the elastomer

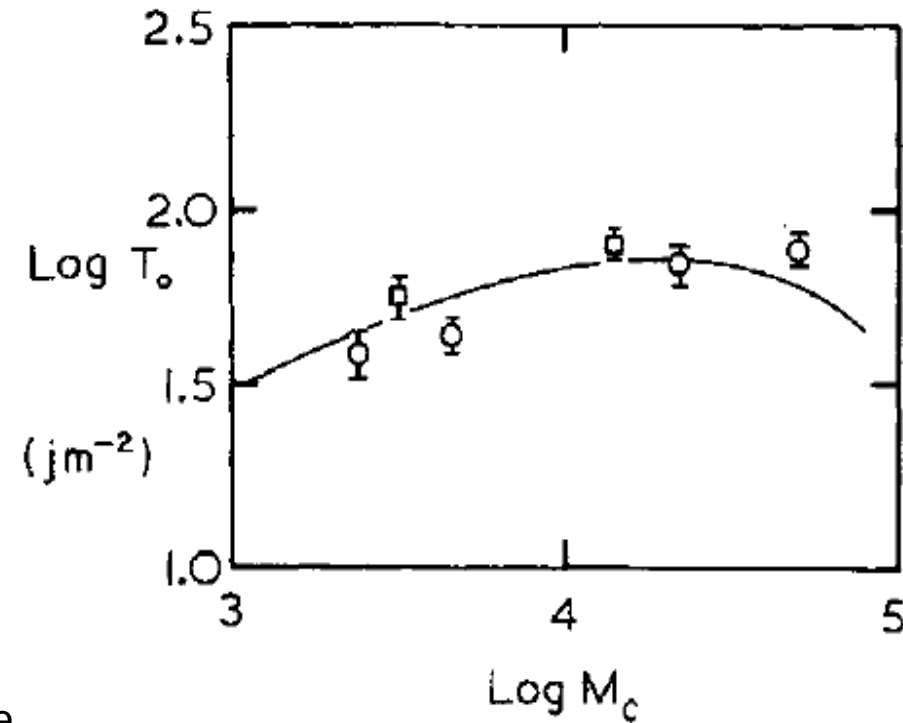
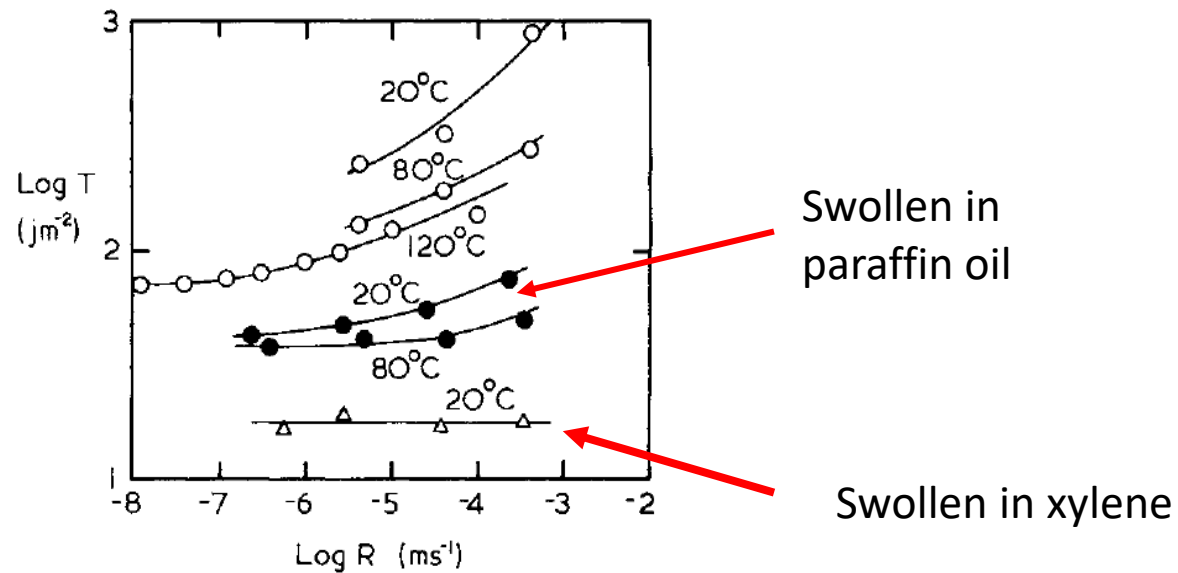
40 – 80 J/m²

Threshold Fracture Energies for Elastomers

A. AHAGON and A. N. GENT, *Institute of Polymer Science, The University of Akron, Akron, Ohio 44325*

Polybutadiene ($T_g = -110^\circ\text{C}$)

Experiments at 20-120°C



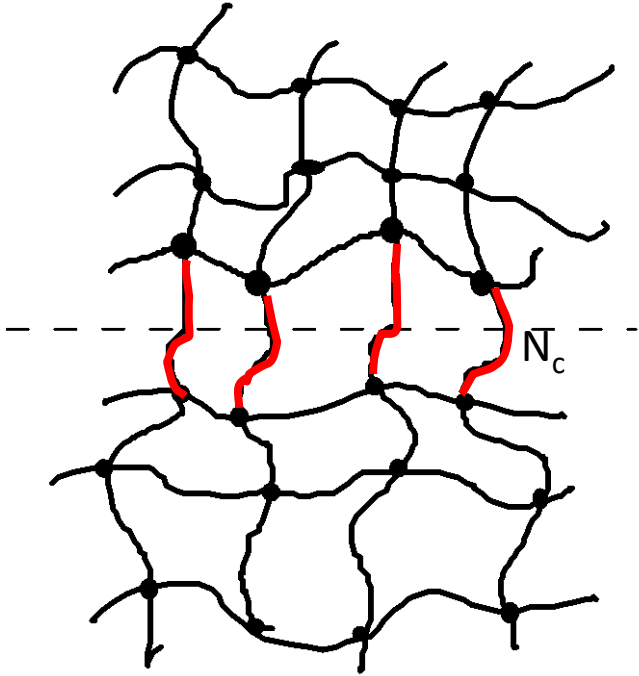
Fracture of bonds in networks: the Lake-Thomas model

$$\Gamma_o = N_c U_b \Sigma$$

N_c = number of monomers

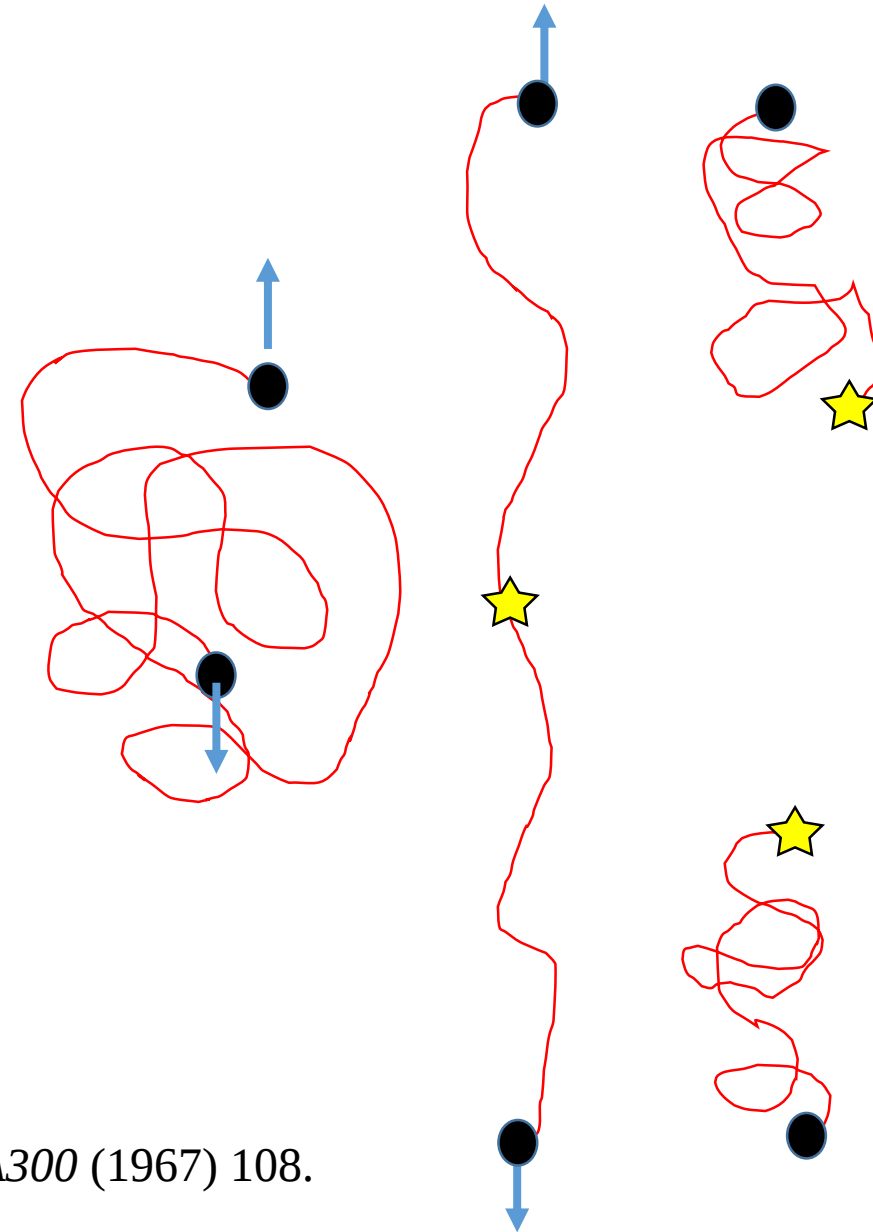
U_b = fracture energy of a covalent bond

Σ = areal density of strands



For rubbers $\Gamma_o \sim 50 \text{ J/m}^2$

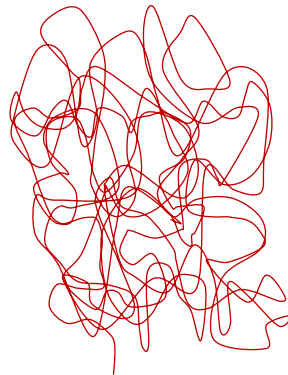
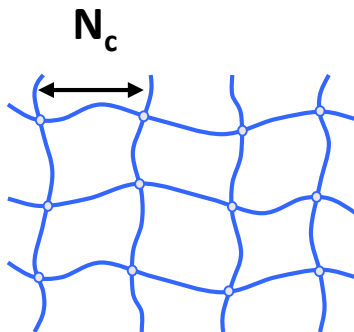
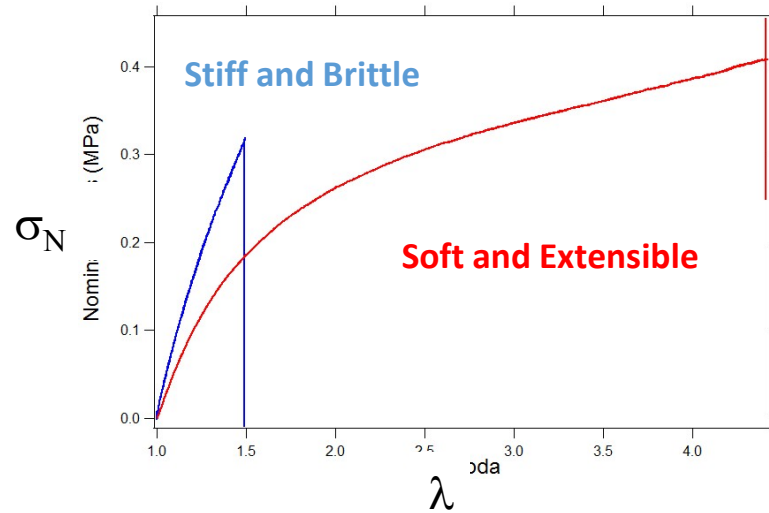
For gels $\Gamma_o \sim 5\text{-}10 \text{ J/m}^2$



G. J. Lake, A. G. Thomas, *Proc. of the Royal Soc. A300* (1967) 108.

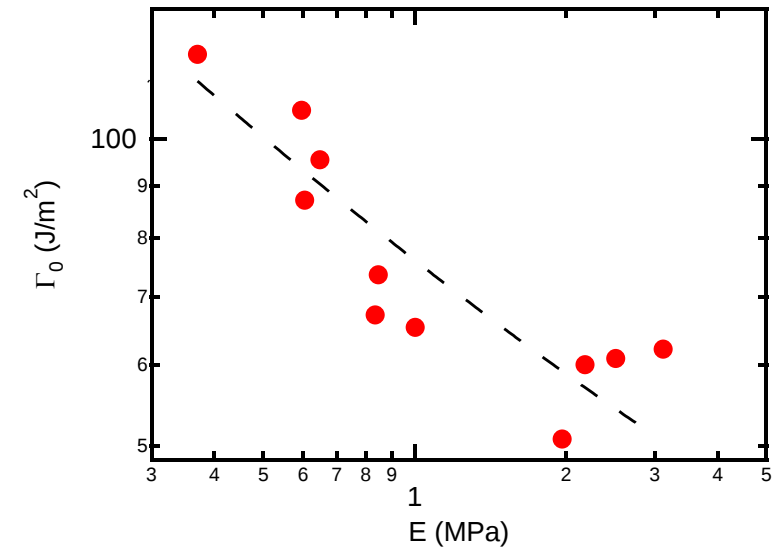
Trade off is found between toughness and stiffness in elastomeric networks and in simple gels

G. J. Lake, A. G. Thomas, *Proc. of the Royal Soc. A300* (1967) 108.



Well predicted by the Lake-Thomas theory

$$\Gamma_o \approx N_c^{1/2} U_b \approx \frac{1}{\sqrt{E}}$$



Bhowmick, A. K.; Gent, A. N.; Pulford, C. T. R., *Rubber Chemistry and Technology* **1983**, *56*, 226-232.

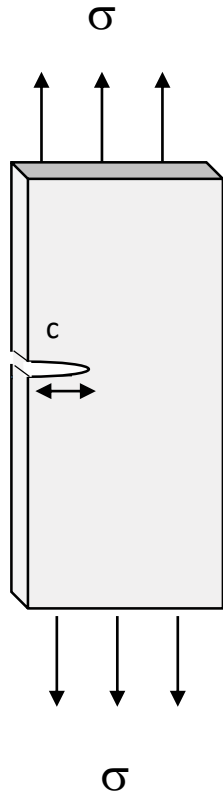
Consequence of Lake-Thomas Model on extensibility

When the crack propagates

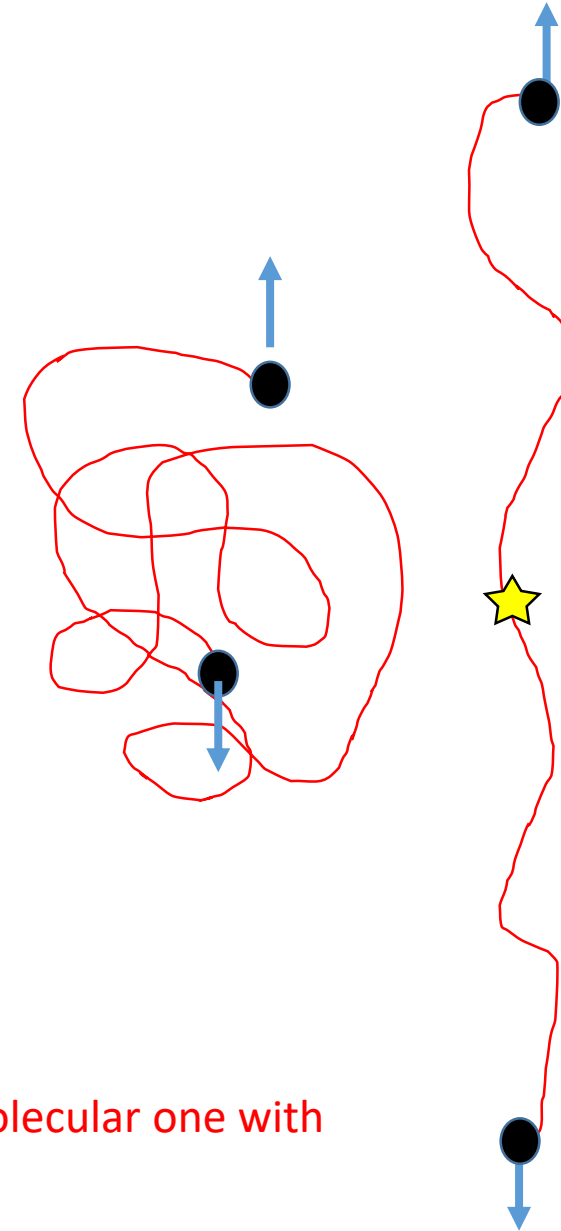
$$\mathcal{G} = \frac{6cW(\lambda_c)}{\sqrt{\lambda_c}} = \Gamma_0 \quad W(\lambda_c) \approx E\lambda_c^2$$

with $\Gamma_0 \approx \frac{1}{\sqrt{E}}$

$$\lambda_c \approx \frac{1}{E} \approx N_c$$



Fracture experiment



Molecular extensibility

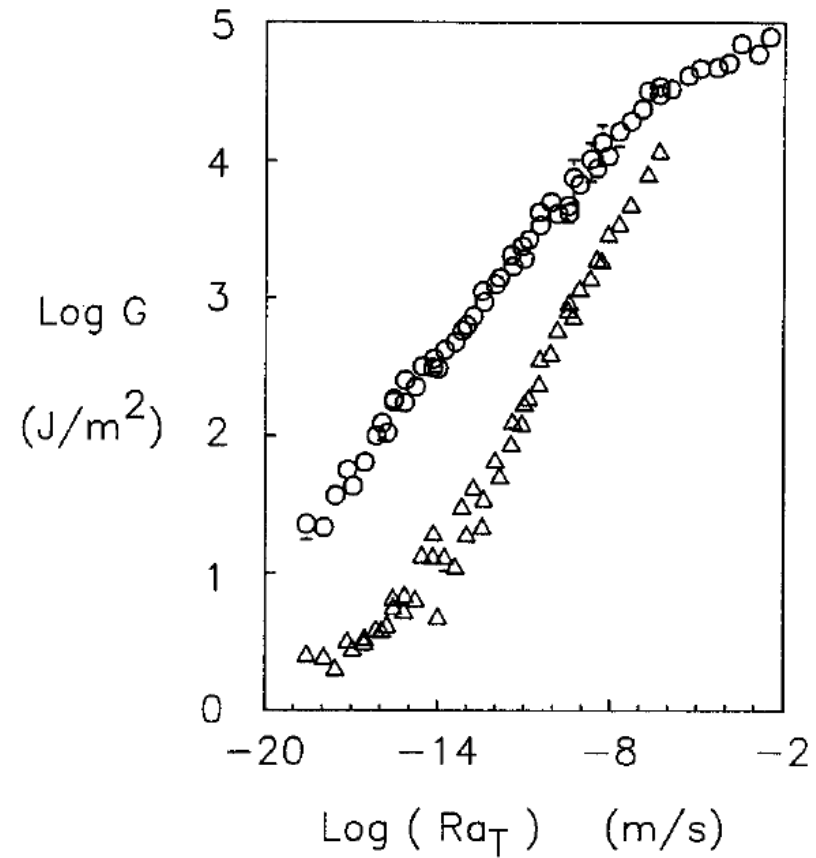
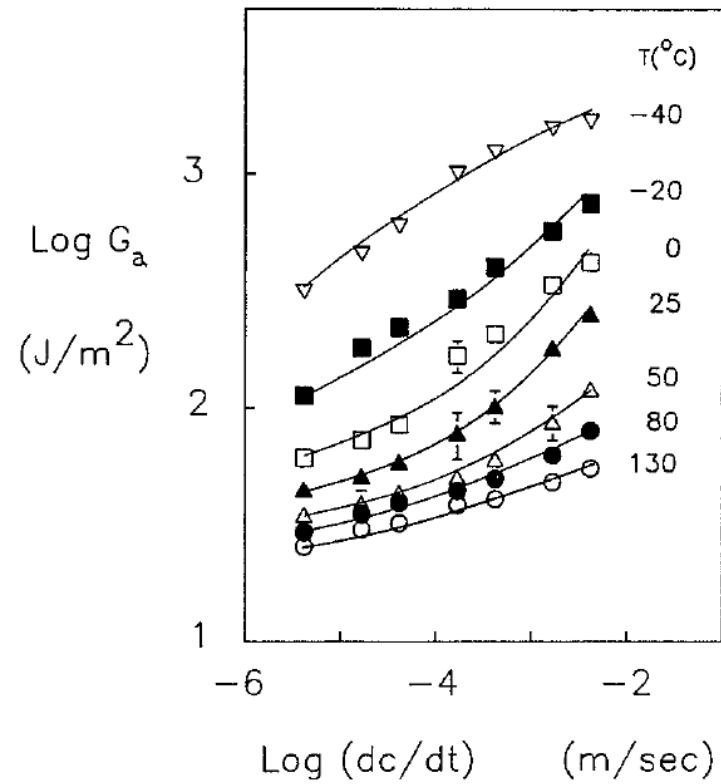
$$\lambda_c \approx \sqrt{N_c}$$

Macroscopic extensibility decreases much more than molecular one with increasing crosslinking

Toughening mechanisms

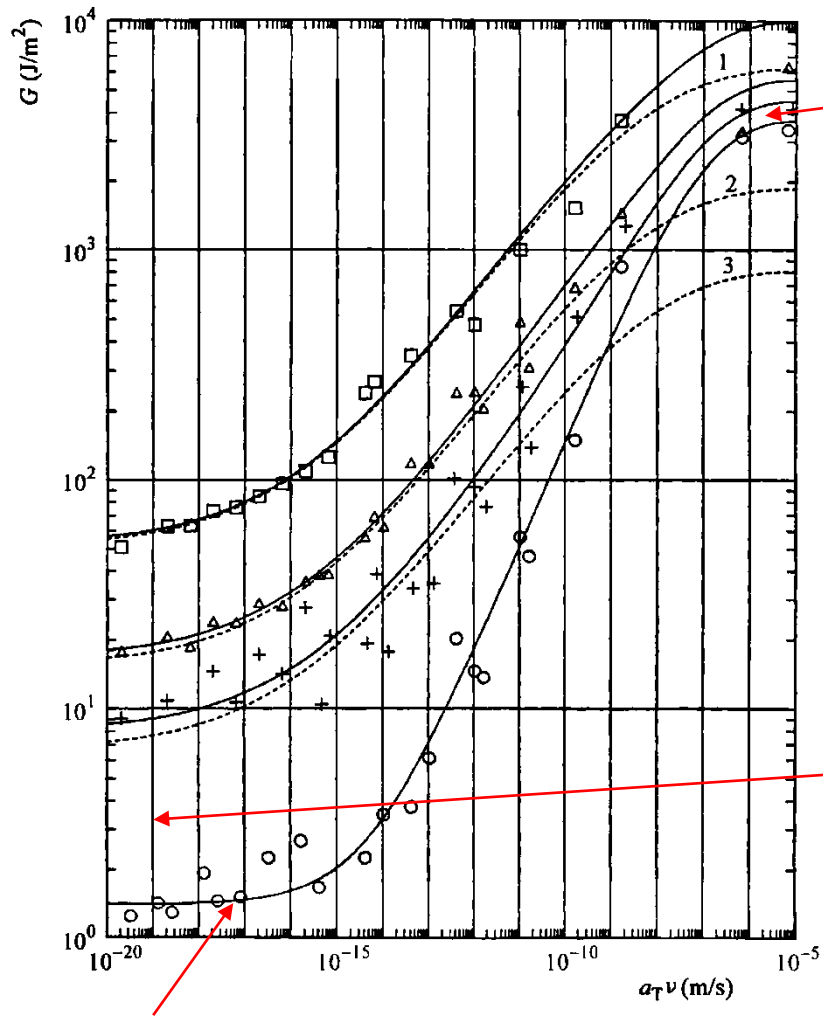
Viscoelastic Dissipation

Rate dependence of fracture energy



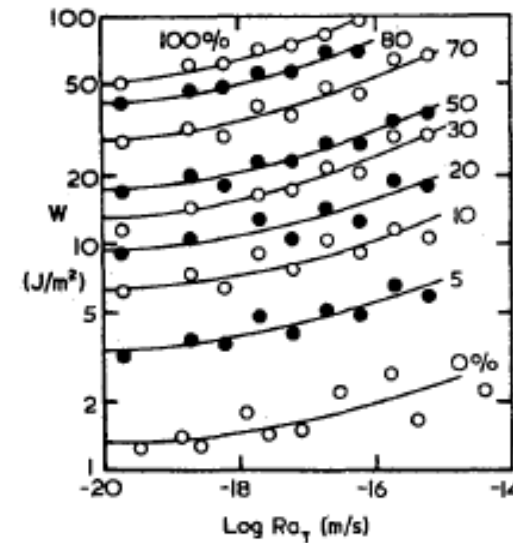
Gent, A. N. *Langmuir* **1996**, *12*, 4492.

Transition between threshold regime and viscoelastic regime



Adherence
(viscoelastic dissipation and large strain damage mechanisms)

$$V_{\text{crack}} \gg 0$$



High temperature
Low rate
region

Bond breakage dissipation

$$V_{\text{crack}} \rightarrow 0$$

Maugis, D., *J. Adhes. Sci. Technol.* **1995**, **9** (7), 1005-1008.

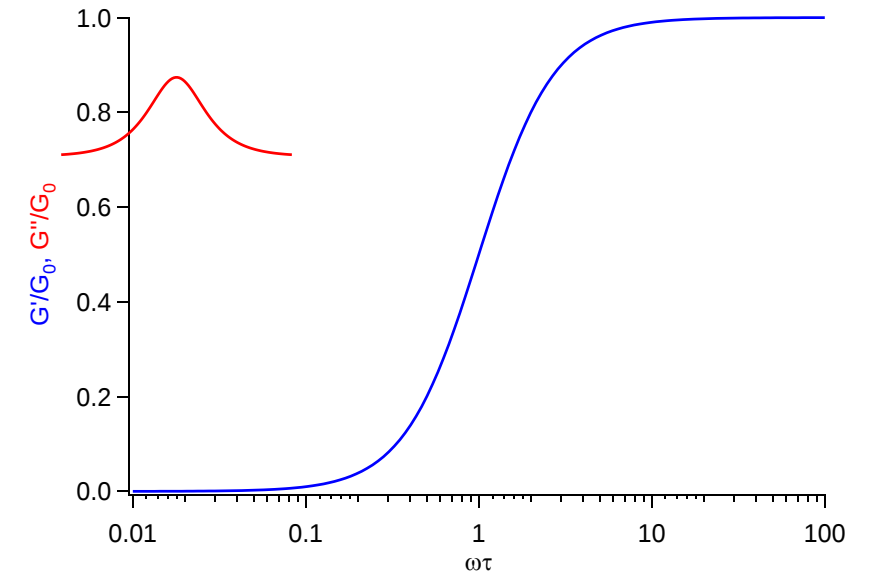
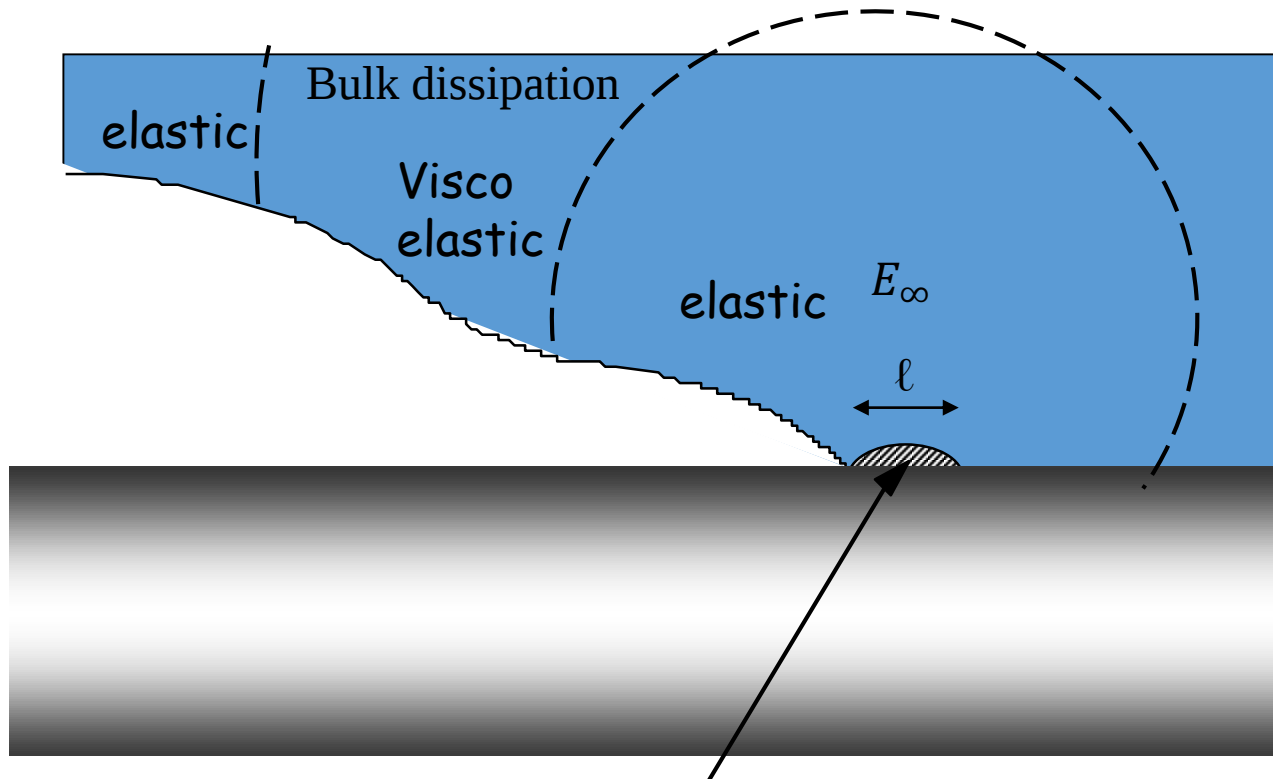
Modeling crack propagation in single relaxation time viscoelastic materials

P. G. de Gennes, *Comptes Rendus de l'Académie des Sciences de Paris, Série II* 307 (1988) 1949.

C. Y. Hui, D. B. Xu, E. J. Kramer, *Journal of Applied Physics* 72 (1992) 3294.

D. B. Xu, C. Y. Hui, E. J. Kramer, *Journal of Applied Physics* 72 (1992) 8.

Persson, B. N. J.; *J. Phys.-Cond. Mat.* **2005**, *17*, (44), R1071-R1142., *Phys Rev E* **2005**, *71*, (3), 036123.



Local non-linear dissipation

2 important parameters: G'' and the size of the dissipative zone

Quantitative result

$$\frac{\Gamma(V)}{\Gamma_0} \cong \mu_\infty \int_{\omega_1}^{\omega_2} \frac{\mu''}{\mu'^2 + \mu''^2} \frac{d\omega}{\omega}$$

Cutoff frequencies:

$$\omega_1 = V/L$$

L = size of the deformed zone

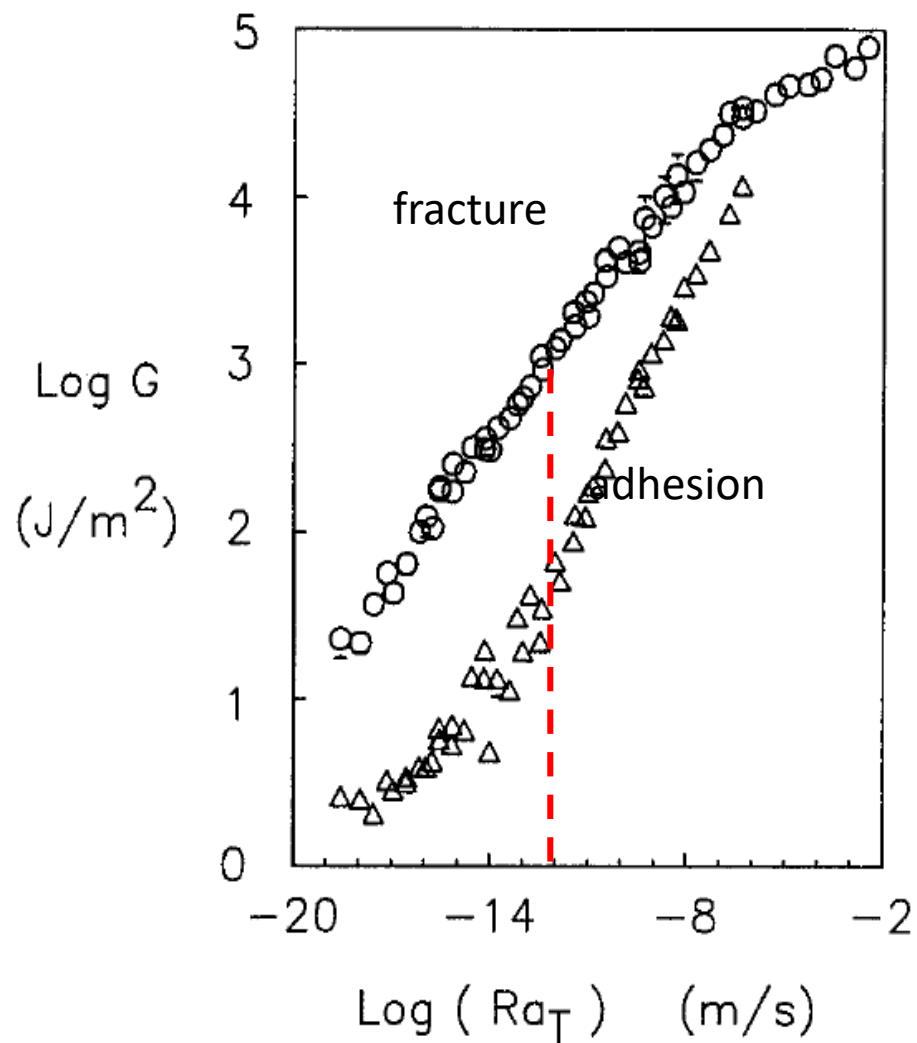
$$\omega_1 = V/\ell$$

ℓ = Size of the zone where
nonlinear deformation is important

In principle: prediction of $\Gamma(V)$ as a function of the linear viscoelastic
Properties of the material

Saulnier, F.; Ondarcuhu, T.; Aradian, A.; Raphael, E. *Macromolecules* 2004, 37, 1067-1075.

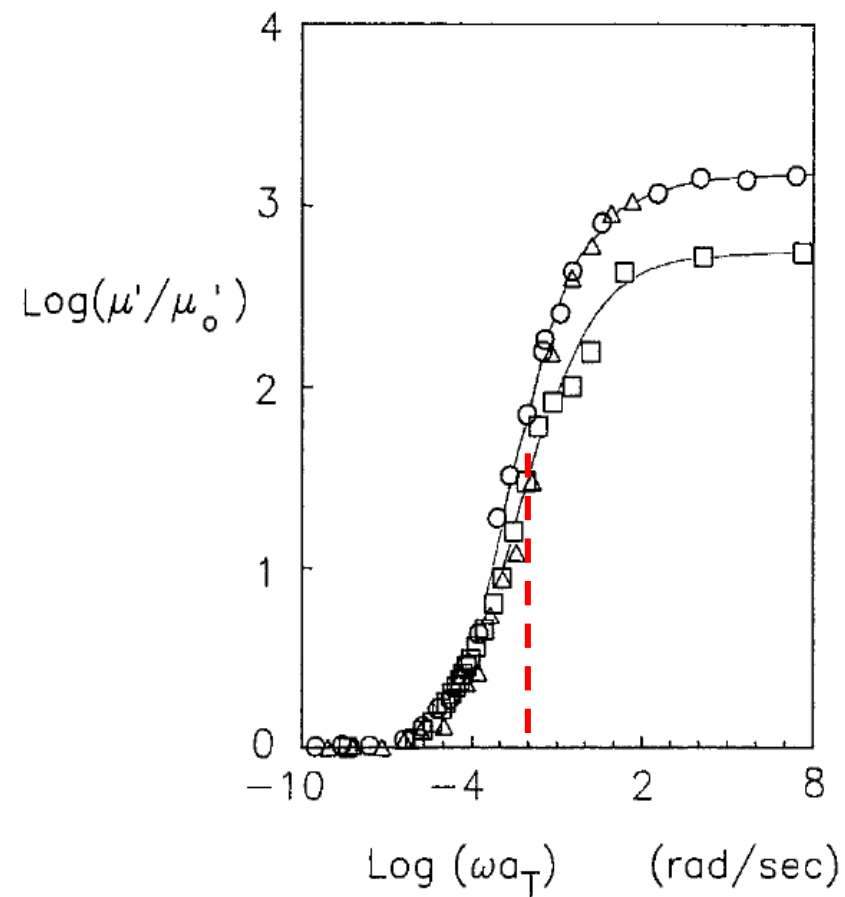
Fracture vs. Crack velocity



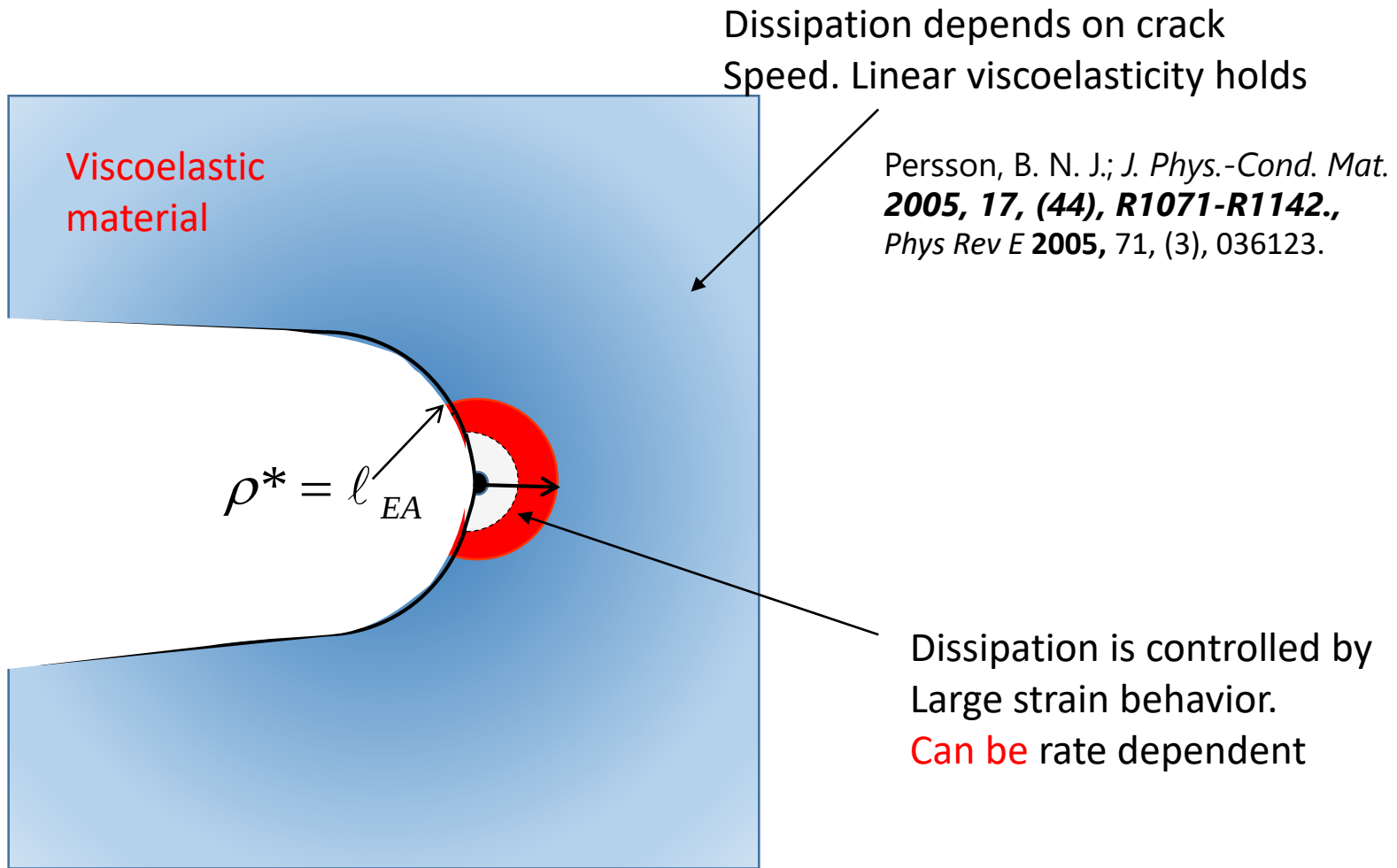
Linear theory: strain rate depends on distance and is given by

$$\dot{\varepsilon} \approx \frac{V}{d}$$

Elastic modulus vs frequency



$$d = 10^{-10} \text{ m}$$



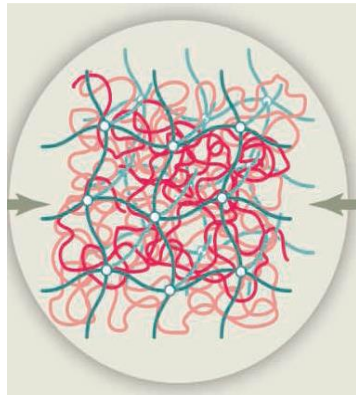
For materials that are very elastic (low $\tan \delta$), in the *linear regime* (gels), this toughening mechanism does not work !

Toughening mechanisms

Sacrificial Bonds

Recent tough and stiff networks: additional sacrificial bonds to dissipate energy

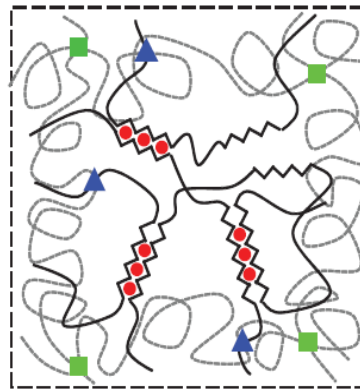
Double covalent networks



Breakable covalent bonds

Gong, J. P. et al. (2003)
Adv. Mat. **15(14): 1155-1158.**

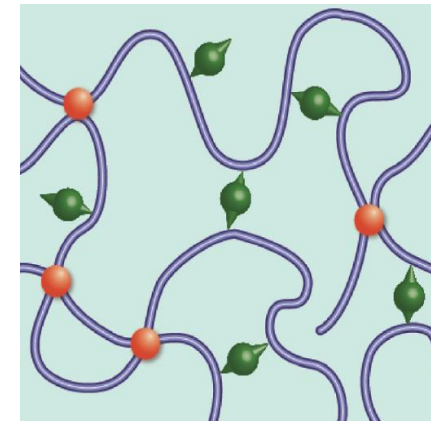
Covalent + Slow bonds



Partially healable and
Breakable ionic bonds

Sun, J.-Y., et al. (2012).
Nature **489(7414): 133-136.**

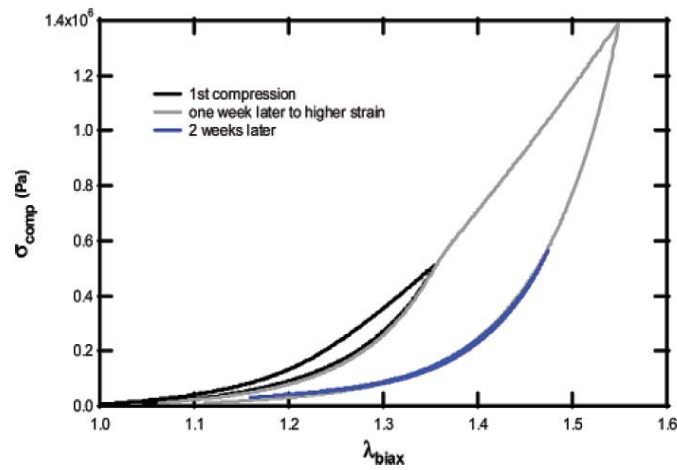
Covalent + fast bonds



Fast healing bonds

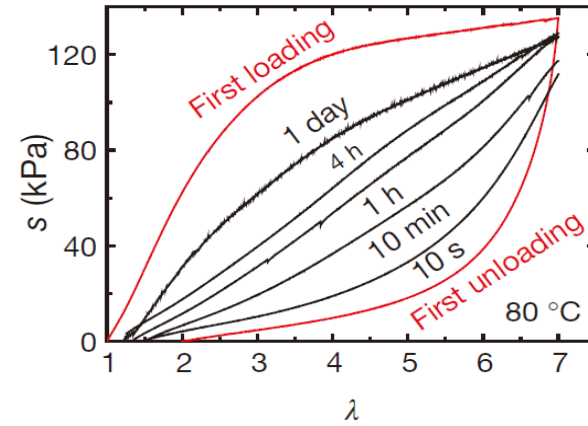
Mayumi, K.; et al.
Extreme Mechanics Letters
2016, 6, 52-59

Non-healing sacrificial bonds



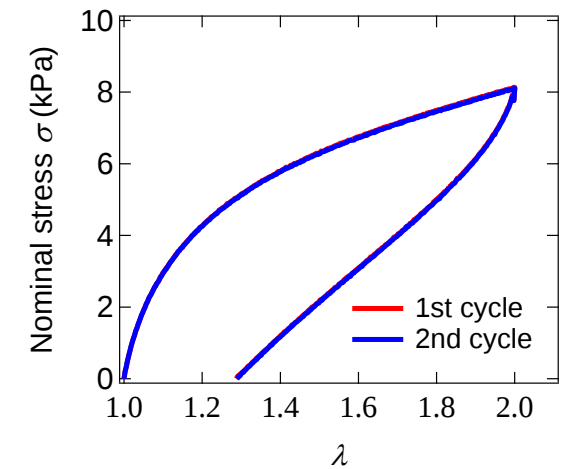
No viscoelastic dissipation

Slow and partial recovery



Large viscoelastic dissipation

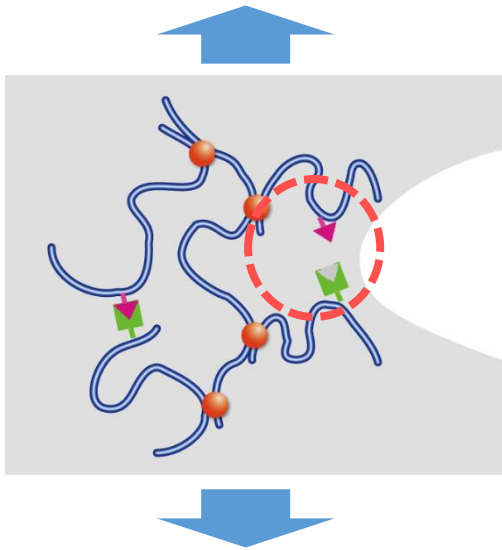
Fast and complete recovery



Viscoelastic dissipation depends on strain rate

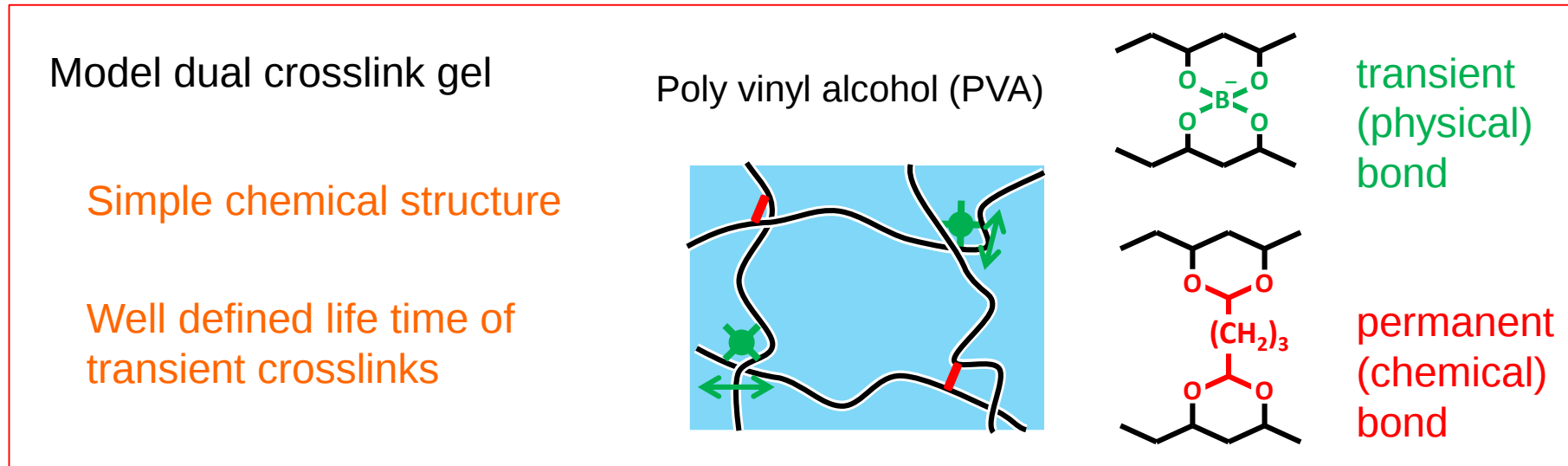
How do we characterize fracture toughness (Γ) of a soft hydrogel with sacrificial bonds by using the energy release rate G ?

The material is not linear elastic, has a strain rate dependent behavior, but no internal friction



How does bond **breaking/healing** dynamics can improve **fracture toughness** for a soft material with no internal friction ?

Hydrogel Model system



PVA solution



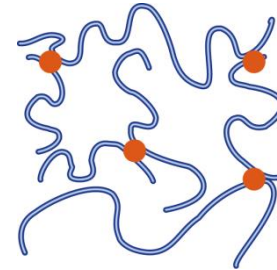
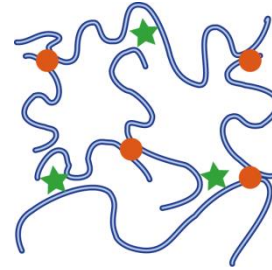
Xlinked by glutaraldehyde (GA)

swollen in water



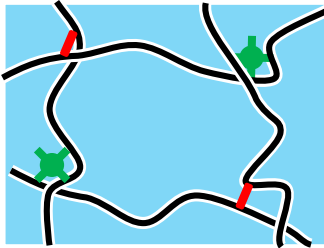
deswollen in Borax/NaCl Solution

12,5 wt% polymer in water

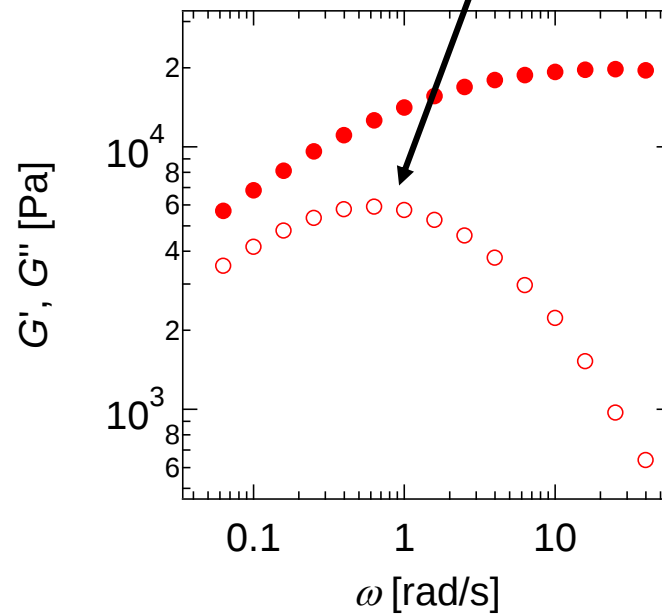


Linear viscoelasticity

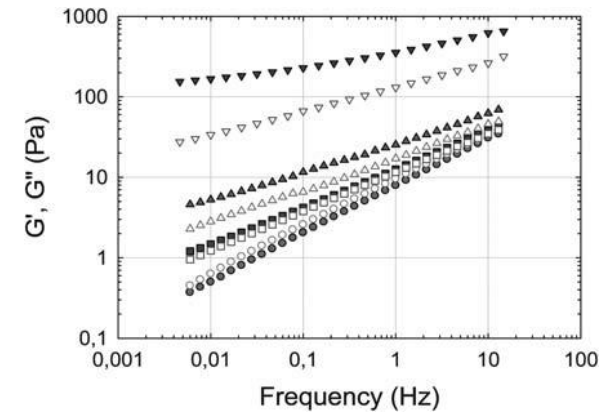
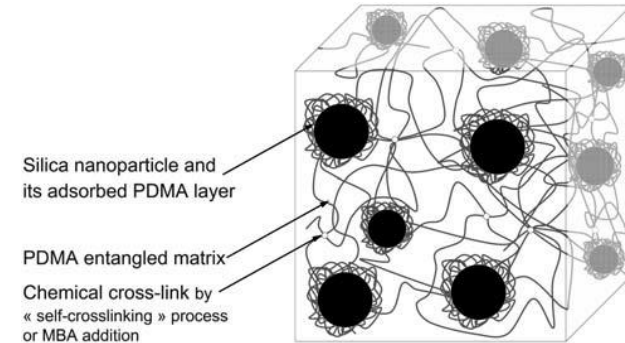
Single Relaxation



Single relaxation time

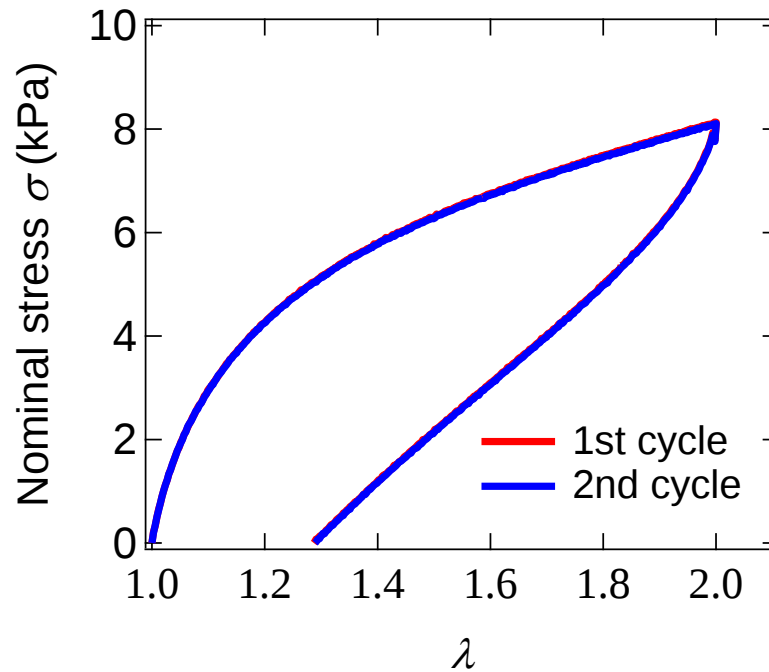
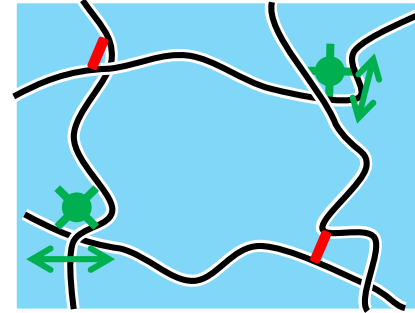
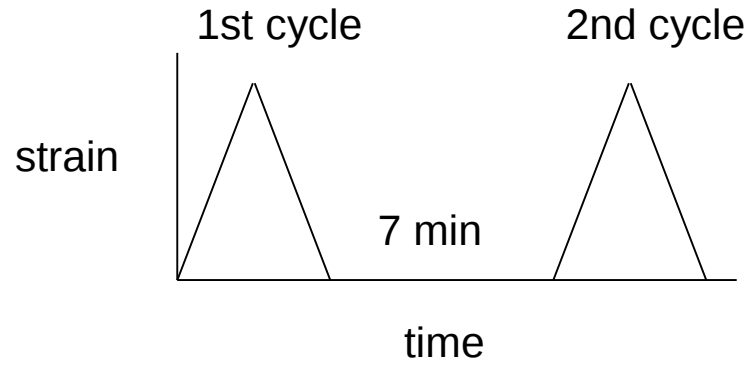


T. Narita, et al., *Macromolecules*, 46, 4174 (2013).



wide distribution of relaxation times

L. Carlsson, *Soft Matter*, 6, 3619 (2010).



Large hysteresis

Perfect recovery

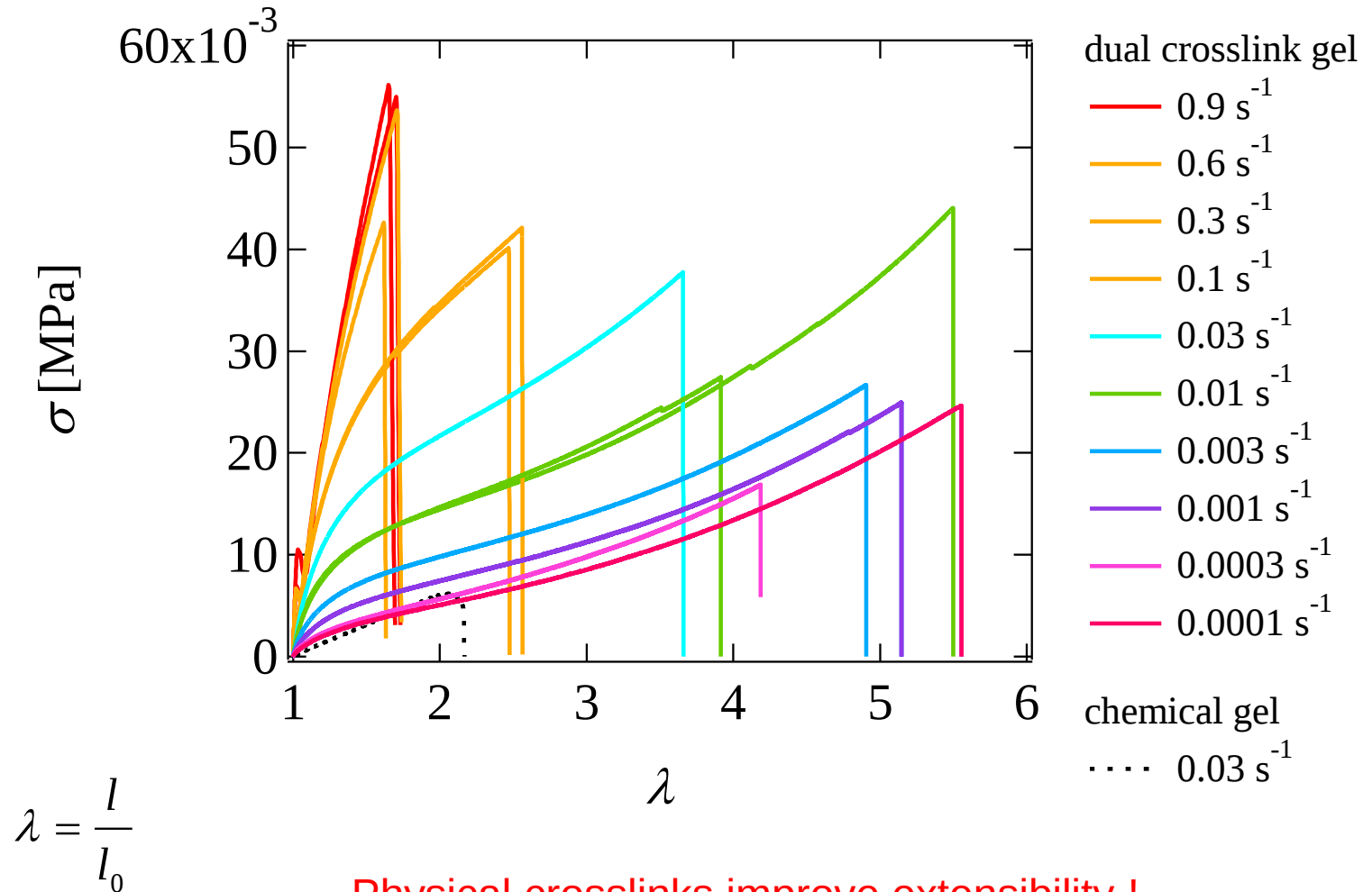
Reversible crosslinks are broken and healed

Loading/unloading curves of hybrid gels. The interval time between cycles was 7 min.

Uniaxial Stretching in oil: strain rate dependence



oil bath → wide range of stretch rates $d\lambda/dt$

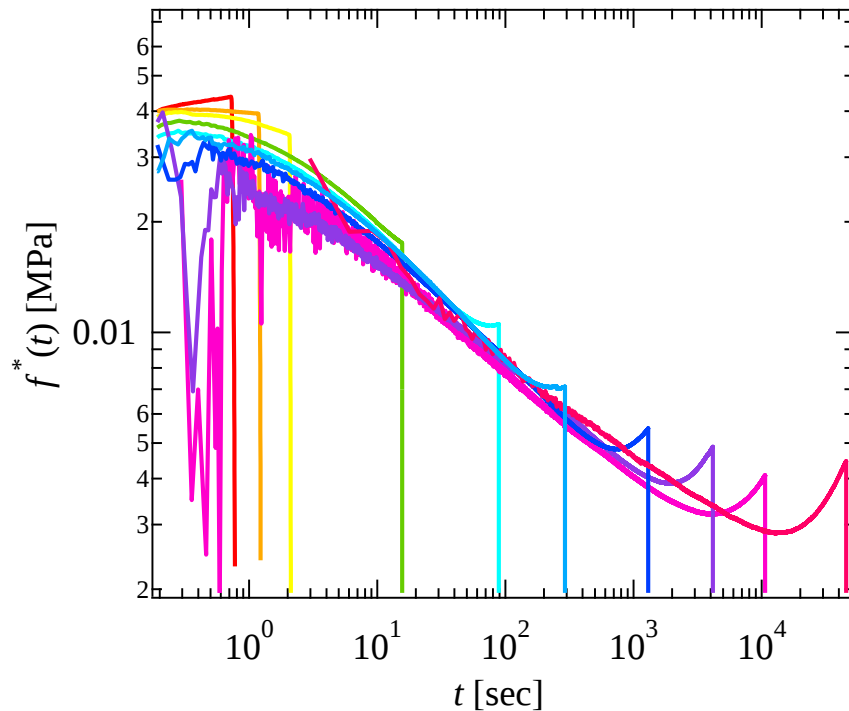


Physical crosslinks improve extensibility !

How can we model the mechanics of the gel ?

Reduced stress $f^* = \frac{\sigma}{\lambda - \lambda^{-2}}$

$$f^*(\lambda, \dot{\epsilon}) \rightarrow f^*(t)$$



- 0.9 s⁻¹
- 0.6 s⁻¹
- 0.3 s⁻¹
- 0.1 s⁻¹
- 0.03 s⁻¹
- 0.01 s⁻¹
- 0.003 s⁻¹
- 0.001 s⁻¹
- 0.0003 s⁻¹
- 0.0001 s⁻¹

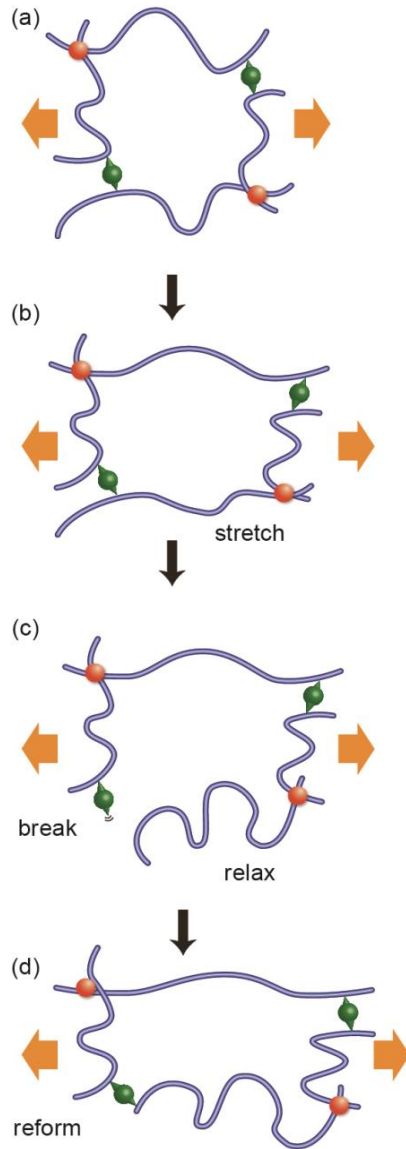
$$\sigma = \underbrace{(\lambda - \lambda^{-2})}_{\text{strain}} \underbrace{f^*}_{\text{time}}$$

Strain does **not** affect
dissociation time of physical
bonds

**Separability of stress
into strain and time terms**

Ingredients of a physically based model

The stress is carried by the stretched chains between bonds

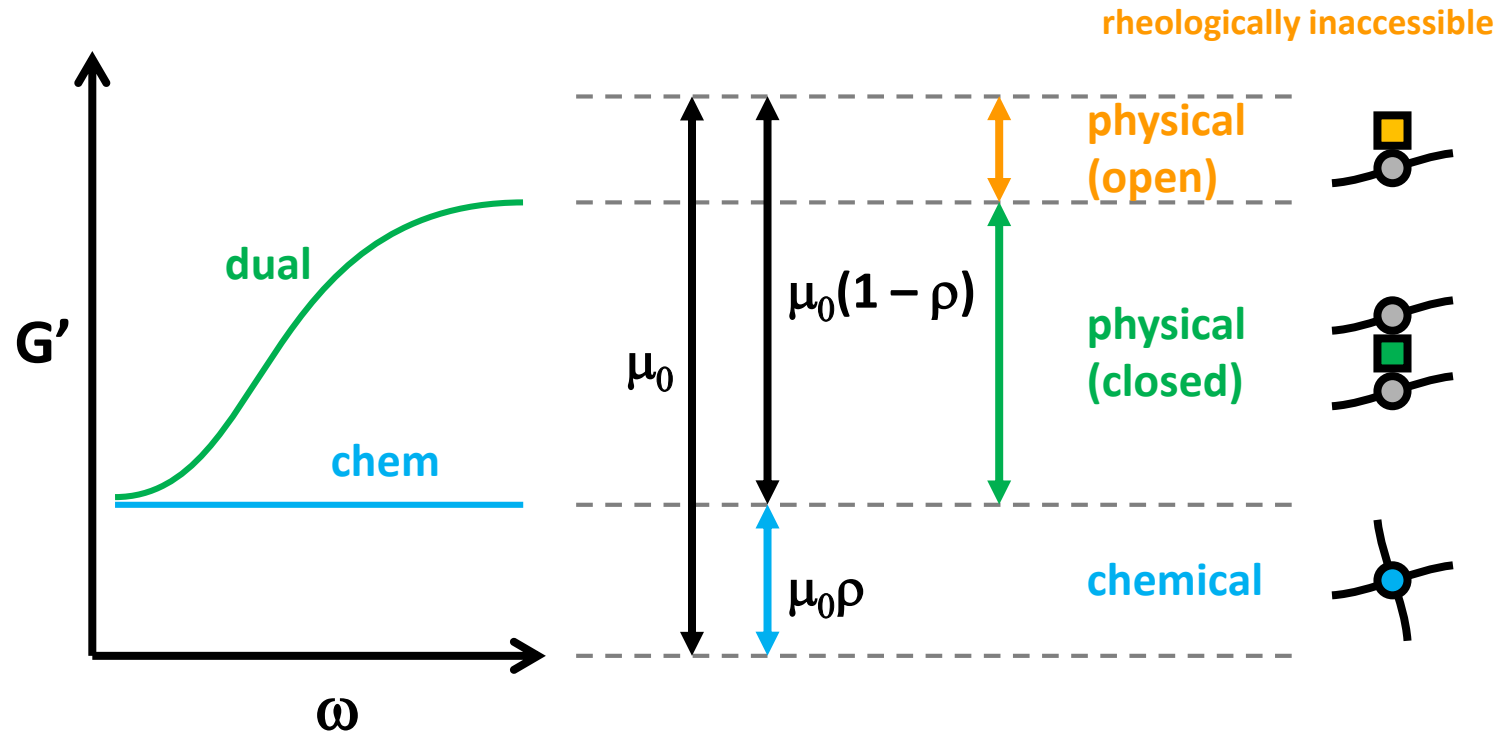


At $t = 0$, all chains are unstretched and $\sigma = 0$

During deformation,

- 1) bonds break and release the stress in the chain.
- 2) Bonds reform (healing) at a different spot and the New chain is unstretched

Physical and Chemical bonds at steady state



R. Long, K. Mayumi, C. Creton, T. Narita and C. Y. Hui, *Macromolecules*, 2014, 47, 7243–7250
Long, R.; Mayumi, K.; Creton, C.; Narita, T.; Hui, C.-Y. *J. Rheology* 2015, 59, 643.
Guo, J.; Long, R.; Mayumi, K.; Hui, C.-Y., *Macromolecules* 2016, 49 (9), 3497-3507.

3-D large strain Model: Rong Long and Herbert Hui

In uniaxial tension

$$\frac{\sigma}{\mu} = [\rho + n(t)] \left[\lambda(t) - \frac{1}{\lambda^2(t)} \right] + \bar{\gamma}_{\infty} \int_0^t \phi_B \left(\frac{t - \tau}{t_B} \right) \left[\frac{\lambda(t)}{\lambda^2(t)} - \frac{\lambda(\tau)}{\lambda^2(\tau)} \right] d\tau$$

Governing equation

Steady state reformation rate of physical bonds

$$\bar{\gamma}_{\infty} = \frac{1 - \rho}{t_H + \frac{t_B}{2 - \alpha_B}}$$

Fraction of closed physical bonds at $t = 0$ and still closed at t

$$n(t) = \bar{\gamma}_{\infty} \frac{t_B}{2 - \alpha_B} \left(1 + (\alpha_B - 1) \frac{t}{t_B} \right)^{\frac{2 - \alpha_B}{1 - \alpha_B}}$$

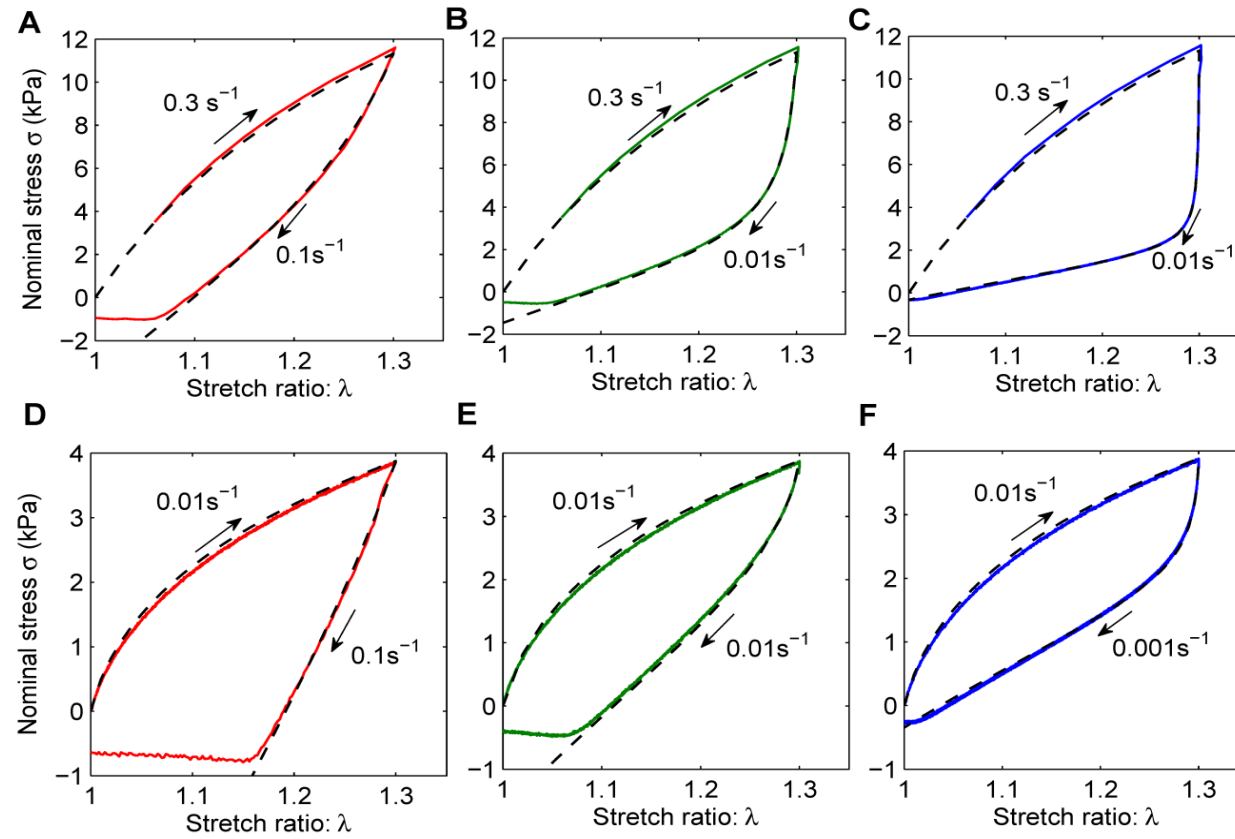
4 fittable parameters

$\mu\rho$

$\mu\bar{\gamma}_{\infty}$

t_B

α_B

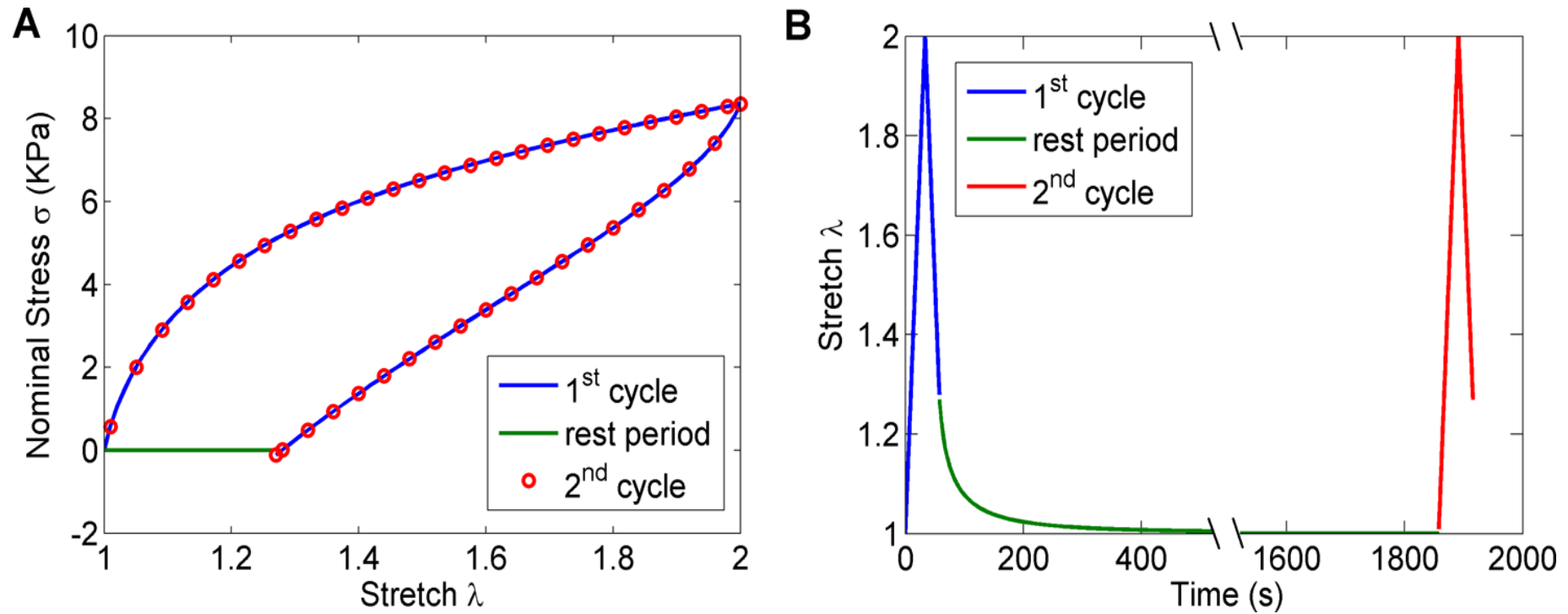


$$\mu\rho = 2.6 \text{ kPa} \quad \mu\bar{\gamma}_{\infty} = 34 \text{ kPa} \quad t_B = 0.24 \text{ s} \quad \alpha_B = 1.6$$

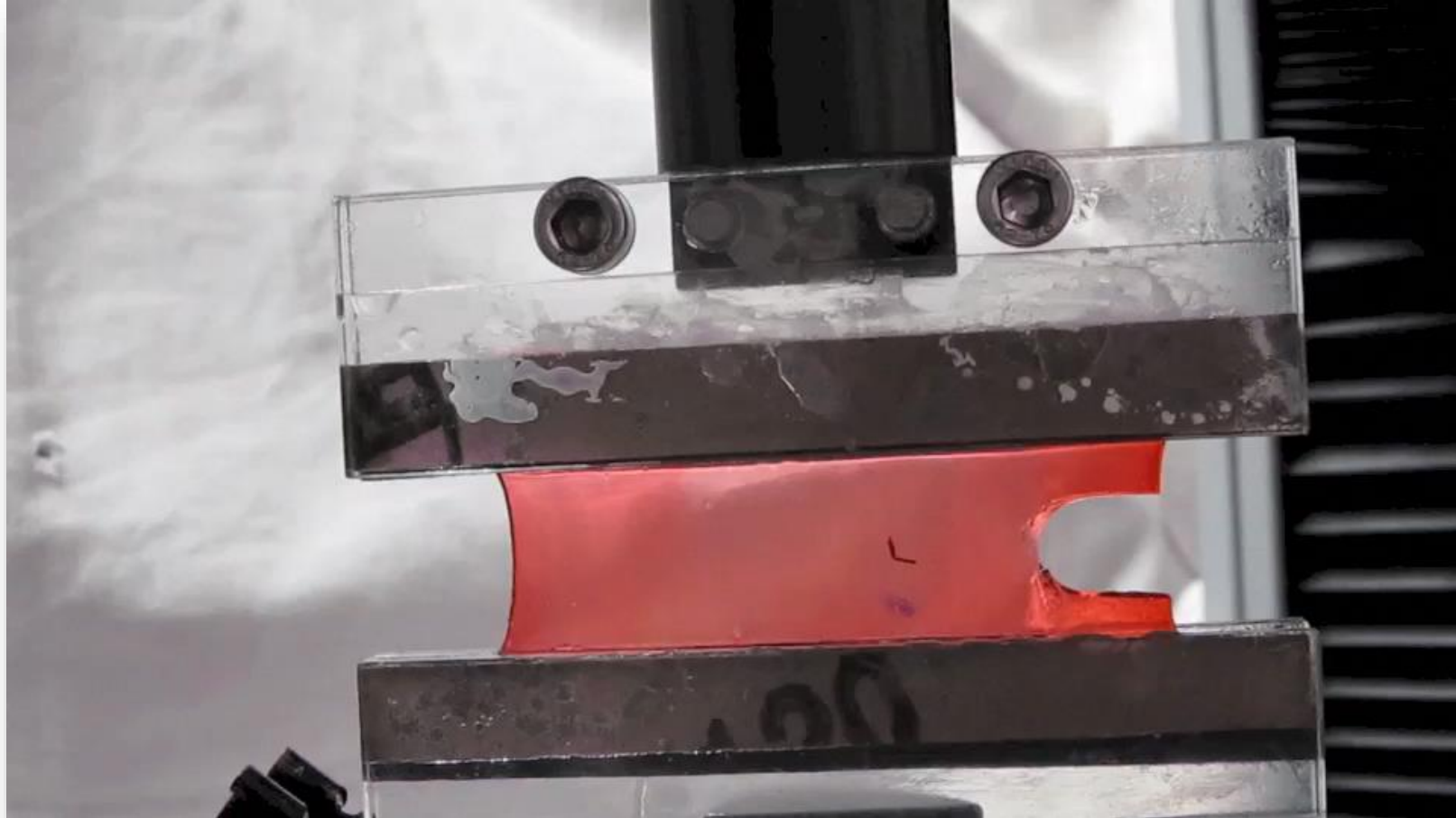
$$t_H = \text{healing time} \quad \bar{\gamma}_{\infty} = \frac{1 - \rho}{t_H + \frac{t_B}{2 - \alpha_B}} \quad t_H = 0.02 \text{ s}$$

The model needs to keep track of the stress carried by each chain

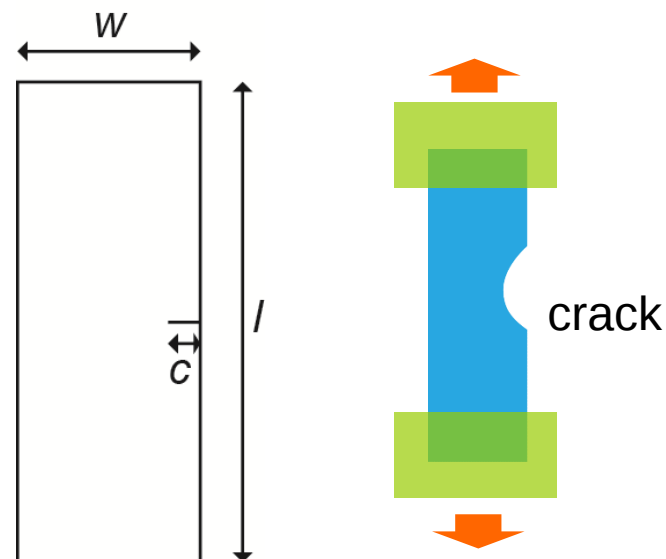
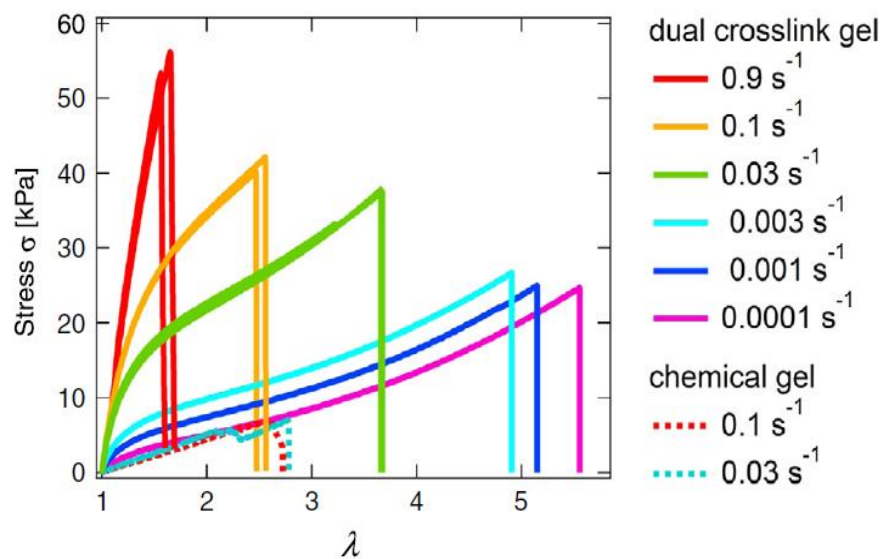
Quantitative predictions of recovery with time with same parameters



How can we use this model to understand fracture ?



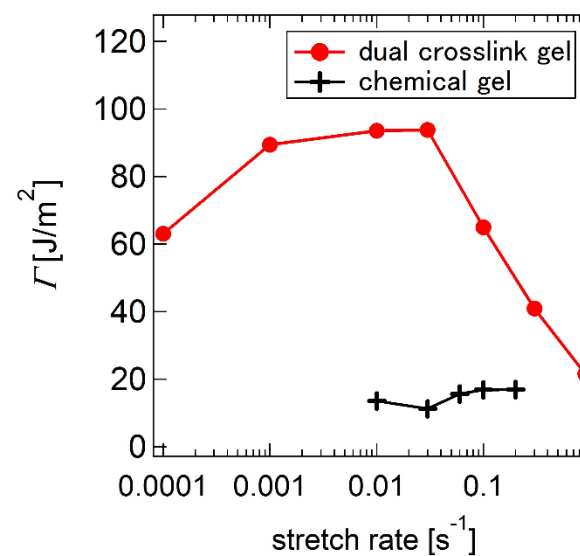
Fracture experiment of the gels



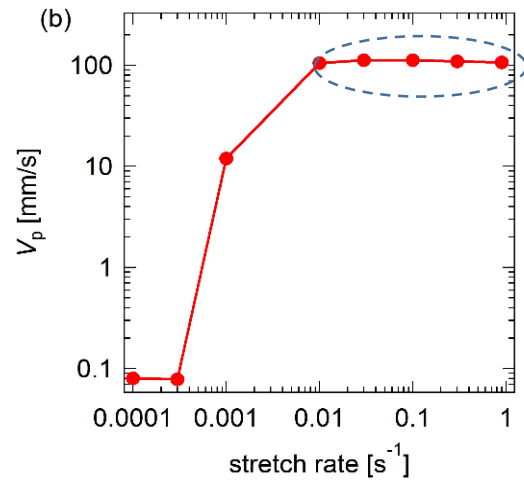
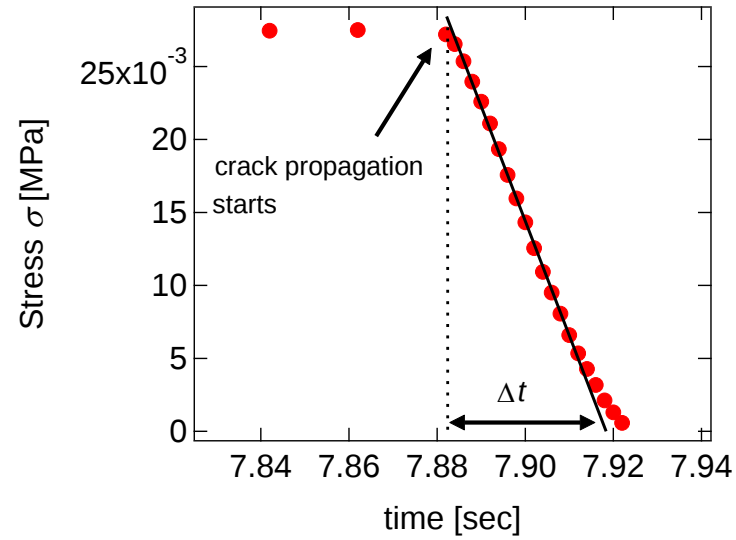
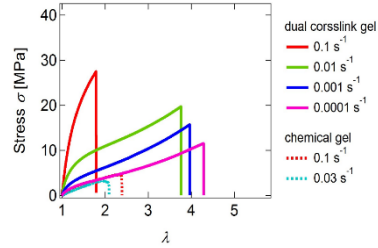
Fracture of notched samples

$$\Gamma = \frac{6}{\sqrt{\lambda_c}} c W (\lambda_c)$$

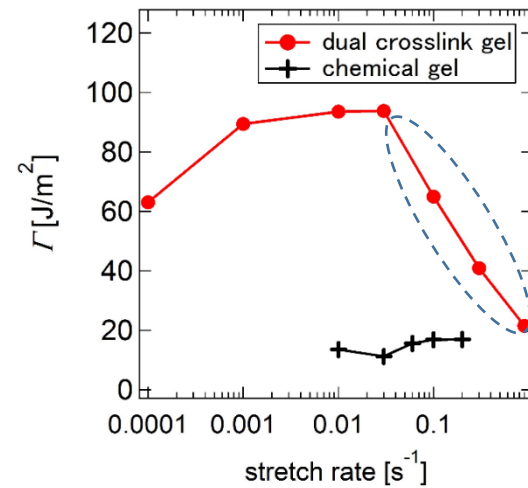
Classical way to calculate Γ

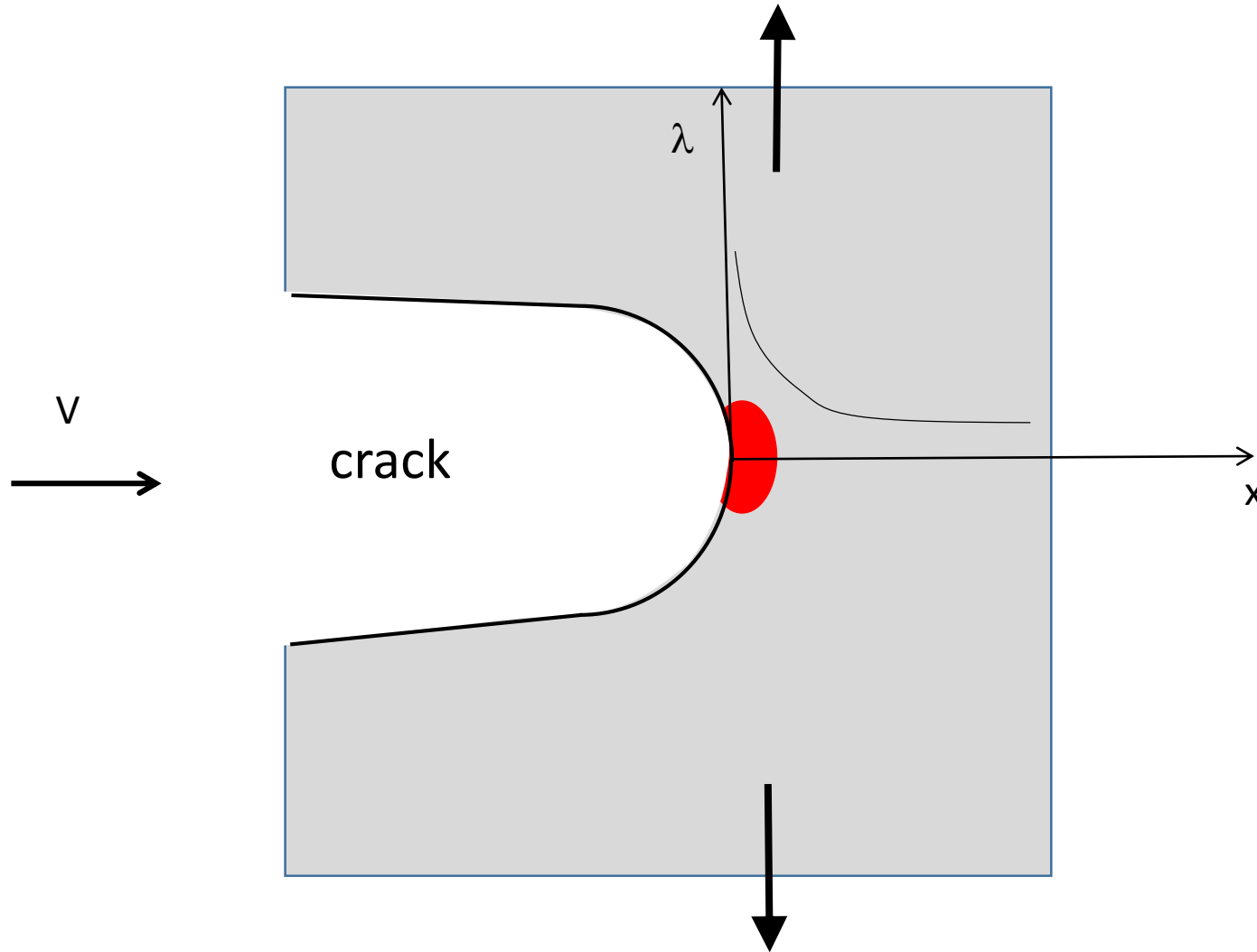


Crack propagation velocity during fracture



No unique $\Gamma(v)$ Relation ?



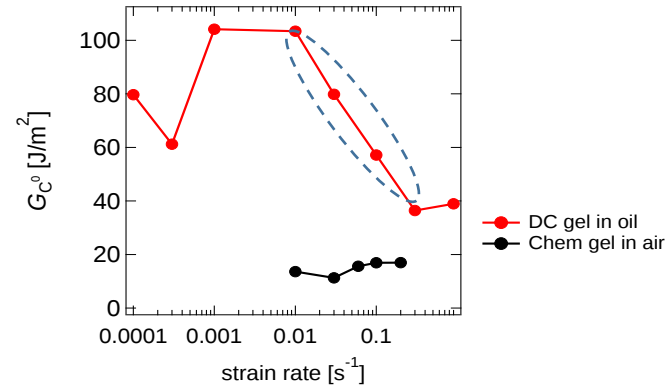
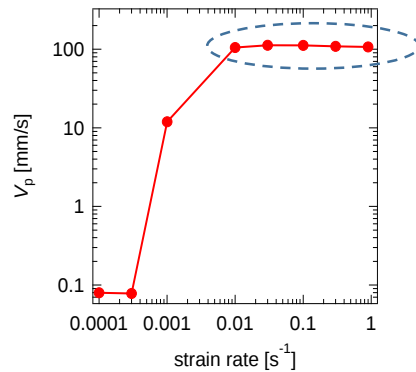


What controls crack propagation ?

Loading rate is controlled by the operator

Unloading rate is controlled by the crack speed

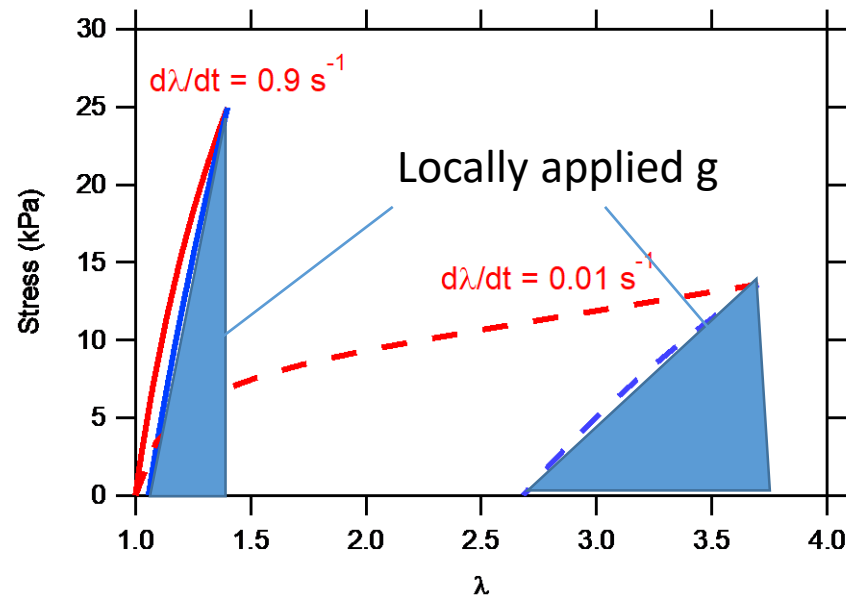
fast regime



Loading rate is variable

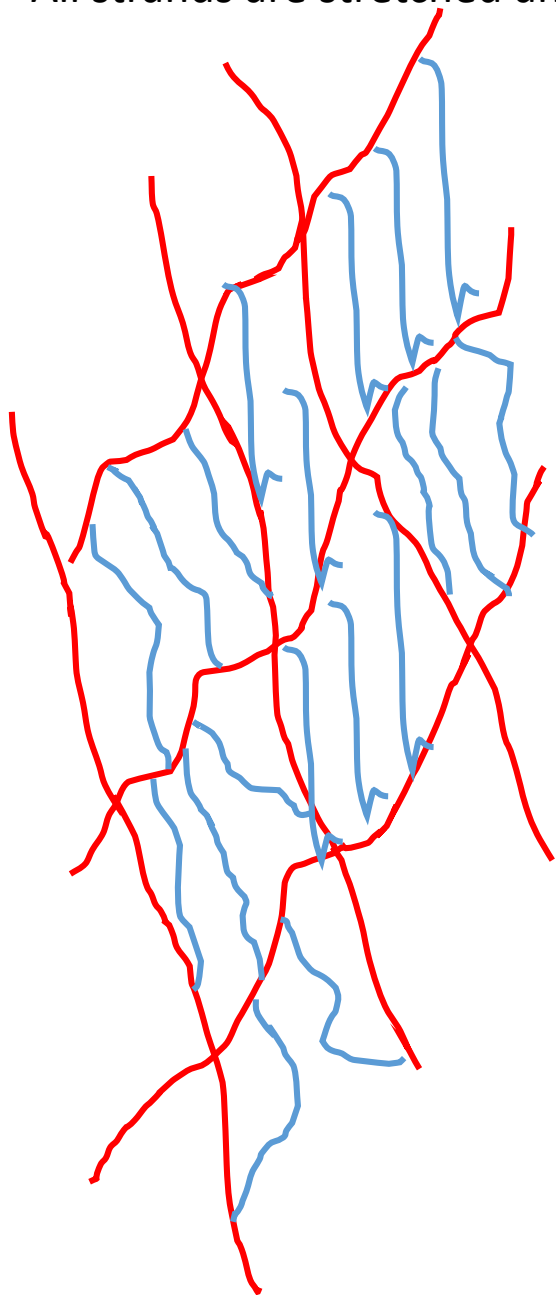
Unloading rate is constant and fast

Use the model to approximately simulate the fracture process:
Controlled loading-fast unloading

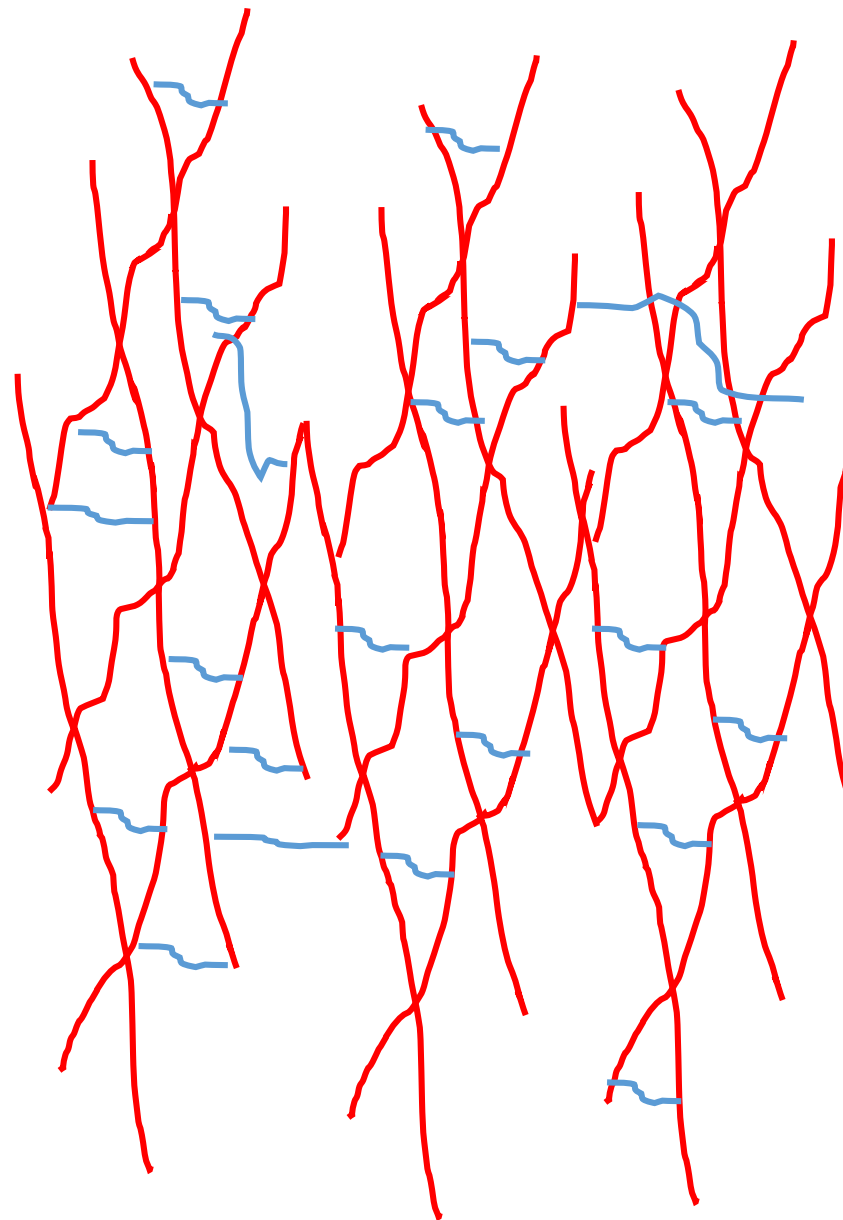


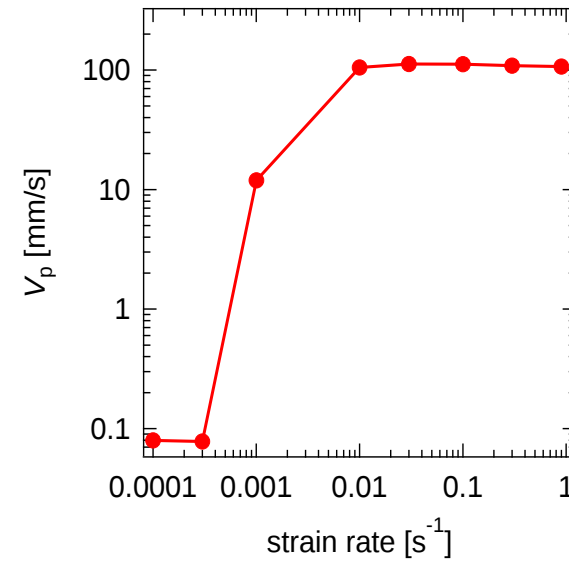
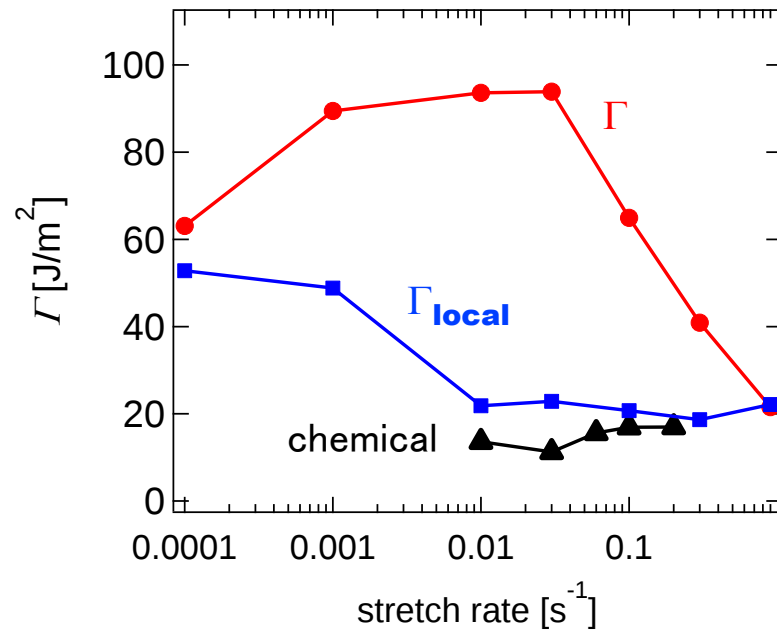
$$\Gamma_{local} = \frac{6}{\sqrt{\lambda_c}} c W_{unloading} (\lambda_c)$$

All strands are stretched and carry load

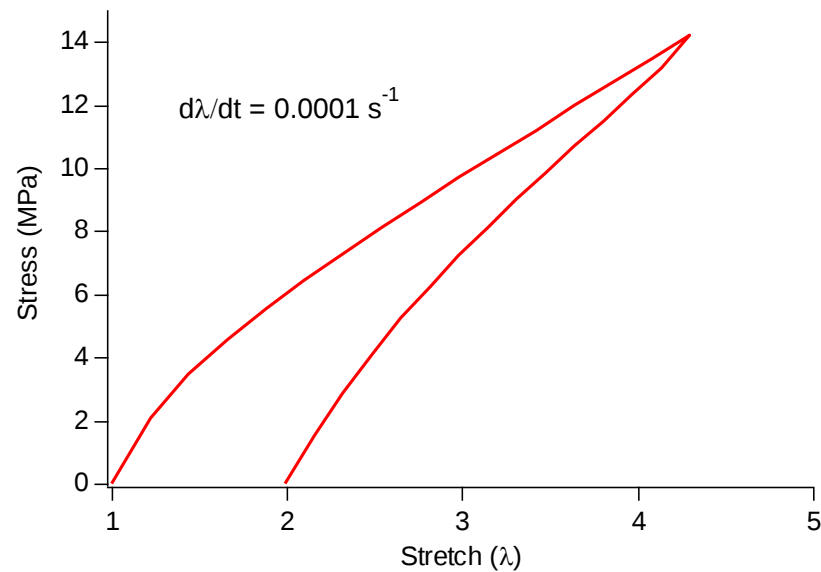


Only red strands carry load





Very slow regime



In this regime physical bonds are not dissipating energy during loading

However they need to be broken !

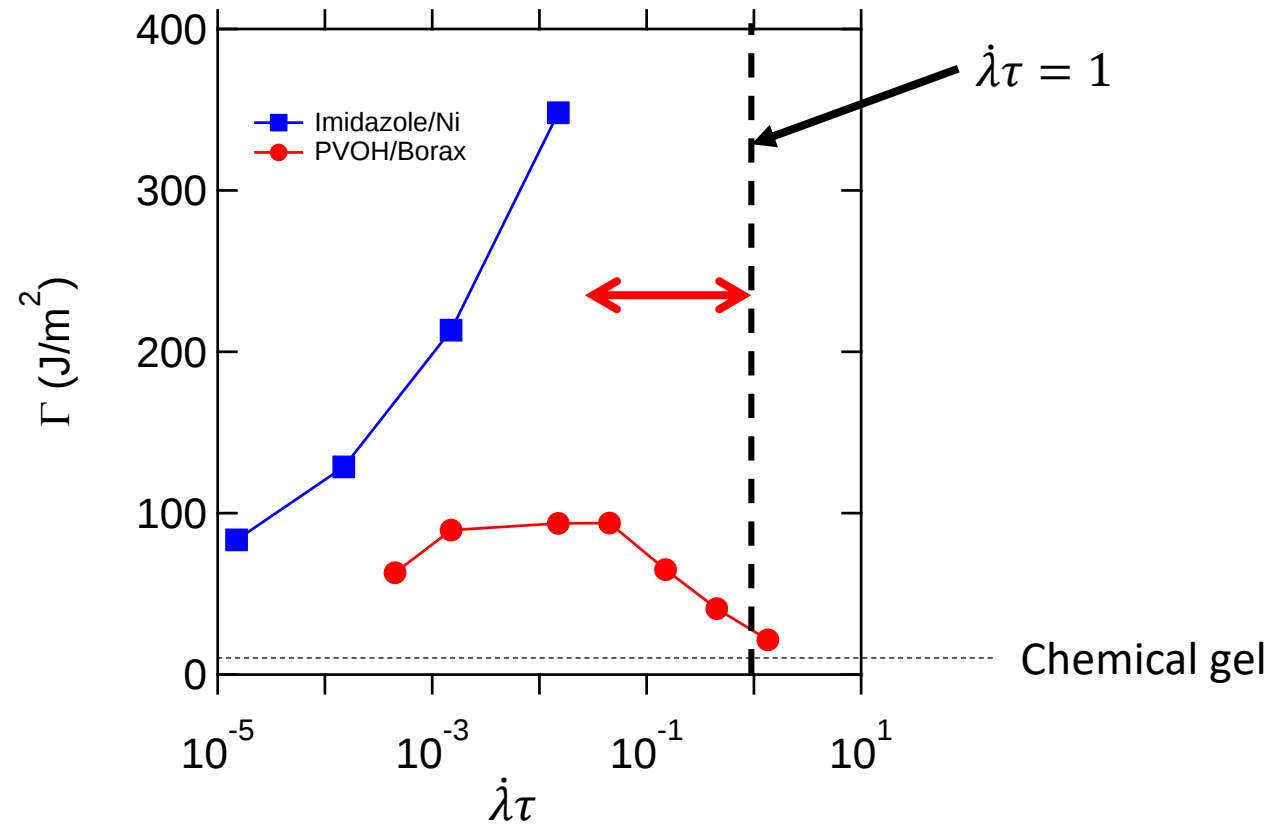
Relation between linear rheology and fracture

Normalized stretch rate

Define relaxation time τ as peak of $G''(\omega)$

Imidazole/ Ni^{++} : $\tau = 0.05$ s

PVOH : $\tau = 1.5$ s

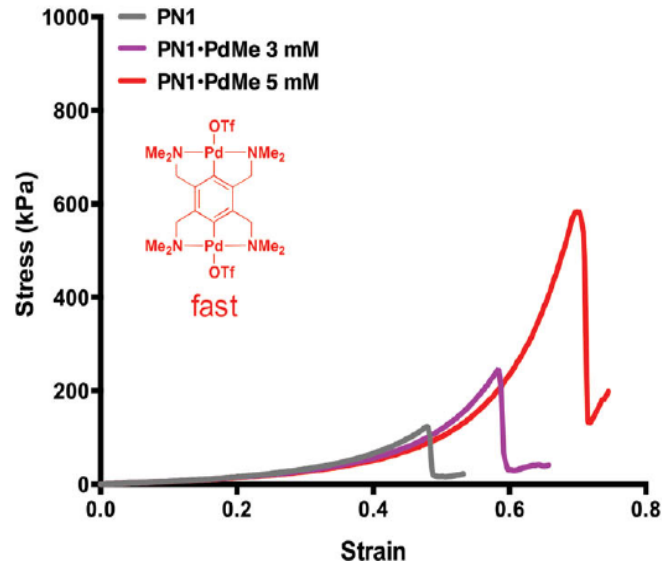


Bonds need to be dynamic to have an effect

Organogels with physical and chemical crosslinks

Uniaxial compression

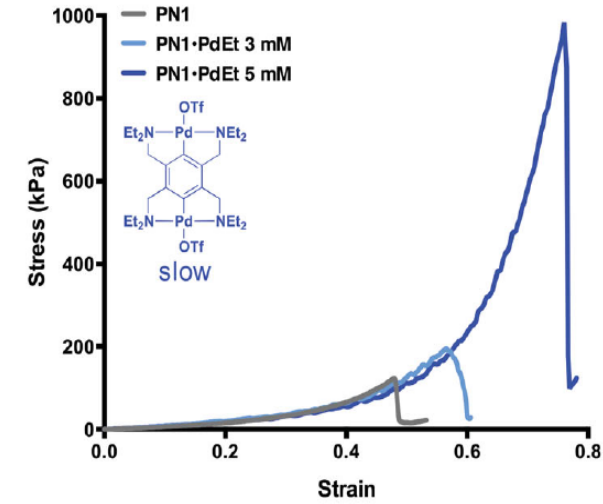
B.



C.

$$\dot{\lambda}\tau = 2 \times 10^{-5}$$

A.

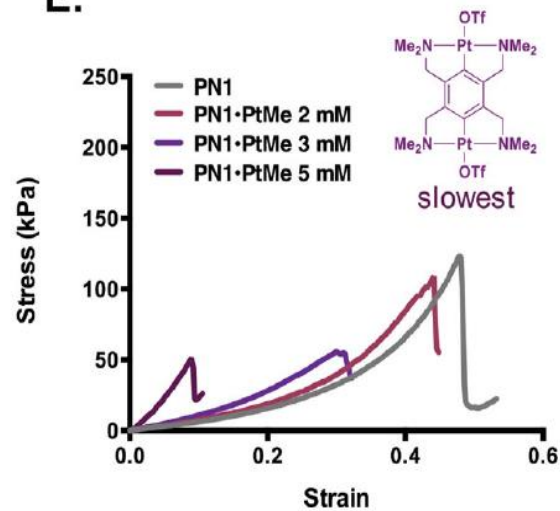


$$\dot{\lambda}\tau = 10^{-3}$$

D.

E.

E.



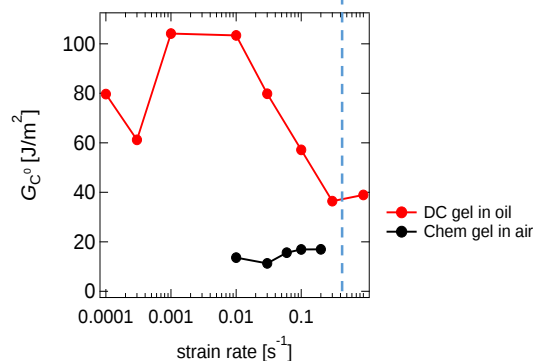
$$\dot{\lambda}\tau = 1$$

Invisible crosslink increase strain and Stress at break

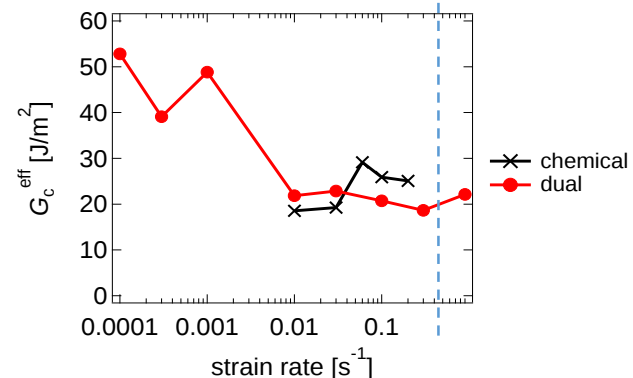
Kean, Z. S.; et al. *Adv Mater* **2014**, *26*, 6013-6018

Take-home messages: fast exchanging bonds

Initiation Γ



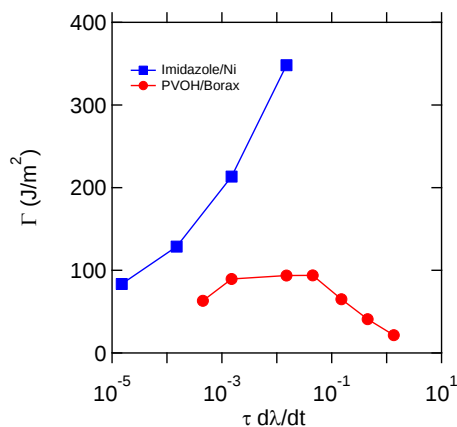
Propagation Γ



$$t_B \sim 0.5 \text{ s}$$

$$\tau \sim 1-2 \text{ s}$$

Molecular mechanisms that change **local structure at the crack tip at fast rates** can have important effects on fracture while being invisible during loading at usual loading rates



Optimum for $\lambda \dot{\tau} \sim 10^{-2}$

Optimized for crack tip strain rates ?